

Applications of gravitational lensing in astrophysics and cosmology

2. Strong lensing analysis

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2. Strong lensing analysis

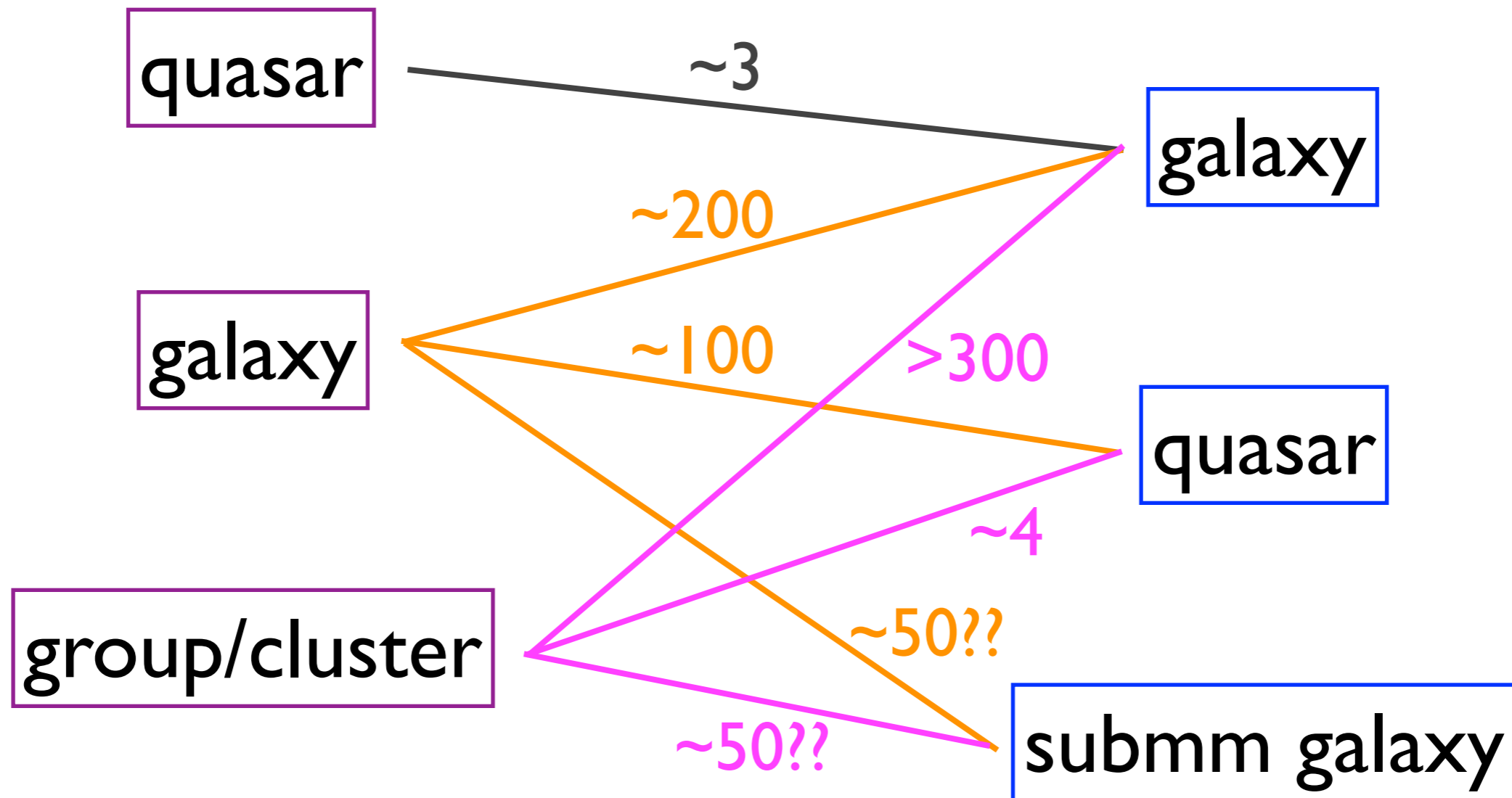
3. Weak lensing analysis

4. Cosmological applications

Strong vs weak lensing

- strong lensing
 - observed for individual sources
 - $\kappa \gtrsim 1$ ($\Sigma \gtrsim \Sigma_{\text{cr}}$), near critical curves/caustics
 - multiple images, high elongation/magnification
- weak lensing
 - observed for ensemble of sources
 - $\kappa \ll 1$ ($\Sigma \ll \Sigma_{\text{cr}}$), far from critical curves/caustics
 - no multiple image, tiny elongation/magnification

Strong lens kinds



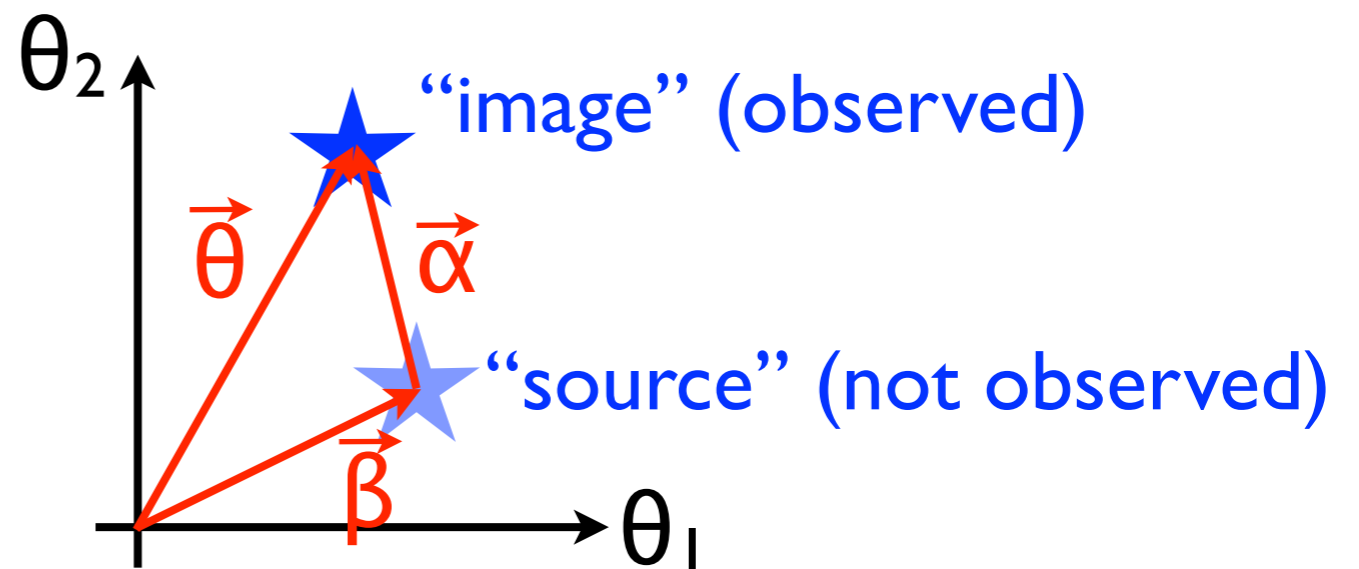
lensing object (lens)

lensed object (source)

Challenge in strong lensing analysis

- lens equation is ‘mapping’ between β and θ

$$\vec{\beta} = \vec{\theta} - \vec{\alpha}(\vec{\theta})$$



- in many cases we want to know $\vec{\theta}$ from $\vec{\beta}$, but it is in general very difficult because
 - lens equation is non-linear in $\vec{\theta}$
 - solution is not unique (**multiple images!**)

Strong lensing analysis

- circular symmetric lenses
- more realistic models
- numerical approach
- modeling strong lens systems

Circular symmetric lenses (I)

- simple yet useful

$$\kappa(\vec{\theta}) = \kappa(\theta) \quad |\vec{\theta}| = \theta$$

then lens potential ψ becomes

$$\begin{aligned} \psi(\vec{\theta}) &= \frac{1}{\pi} \int_0^\infty d\theta' \theta' \kappa(\theta') \int_0^{2\pi} d\phi \ln |\vec{\theta} - \vec{\theta}'| \\ &= 2 \int_0^\theta d\theta' \theta' \kappa(\theta') \ln \left(\frac{\theta}{\theta'} \right) \end{aligned}$$

$$\rightarrow \psi(\vec{\theta}) = \psi(\theta)$$

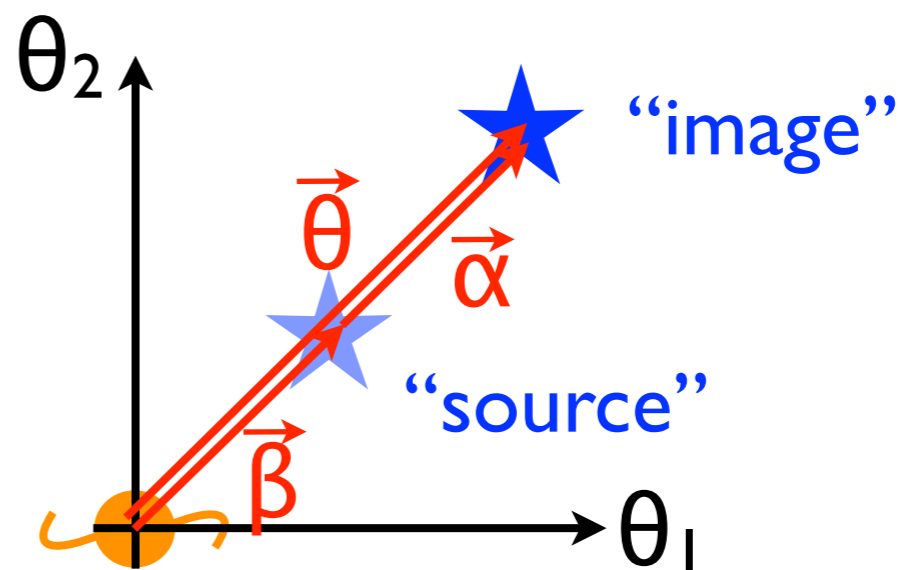
Circular symmetric lenses (II)

- deflection angle

$$\vec{\alpha}(\vec{\theta}) = \vec{\nabla} \psi(\theta) = \underbrace{\left[\frac{2}{\theta^2} \int_0^\theta d\theta' \theta' \kappa(\theta') \right]}_{= \bar{\kappa}(< \theta)} \vec{\theta}$$

$$\rightarrow \vec{\alpha}(\vec{\theta}) \parallel \vec{\theta}$$

$$\alpha(\theta) = \theta \bar{\kappa}(< \theta)$$

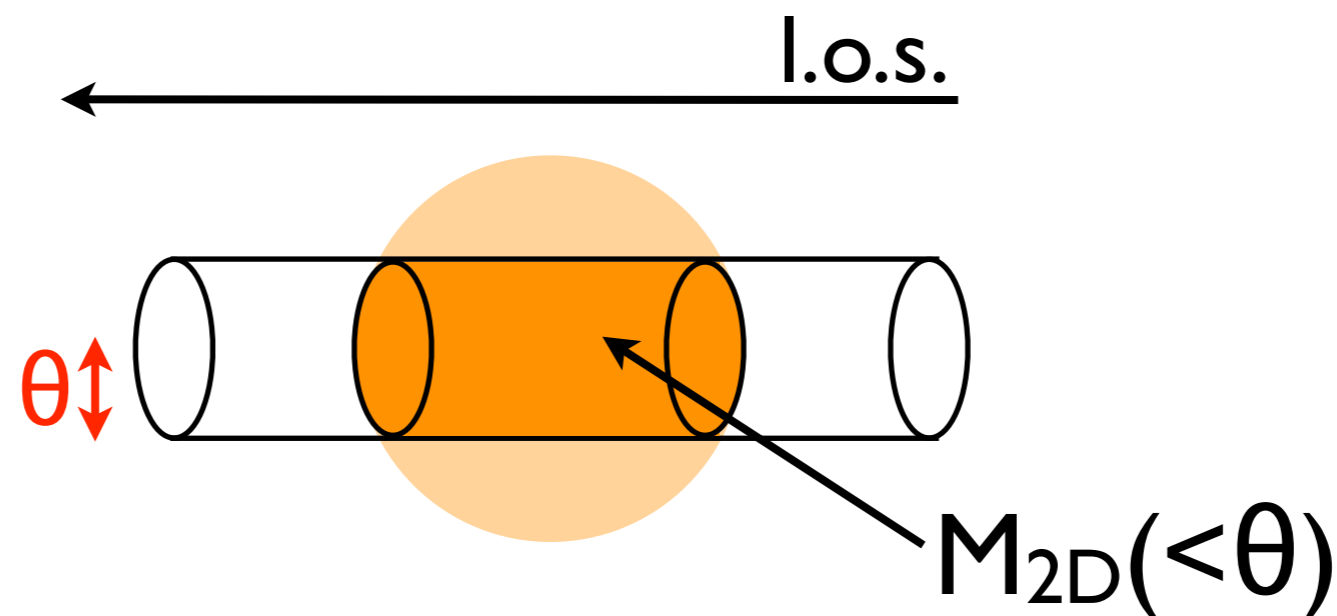


Circular symmetric lenses (III)

- therefore, lens equation reduces to 1D eq.

$$\beta = \theta - \alpha(\theta) = [1 - \bar{\kappa}(< \theta)] \theta$$

note: $\bar{\kappa}(< \theta) = \frac{M_{2D}(< \theta)}{\pi \theta^2 D_A^2(z_l) \Sigma_{\text{cr}}}$



Circular symmetric lenses (IV)

- shear [polar coords $(\theta_1, \theta_2) = (\theta \cos \phi, \theta \sin \phi)$]

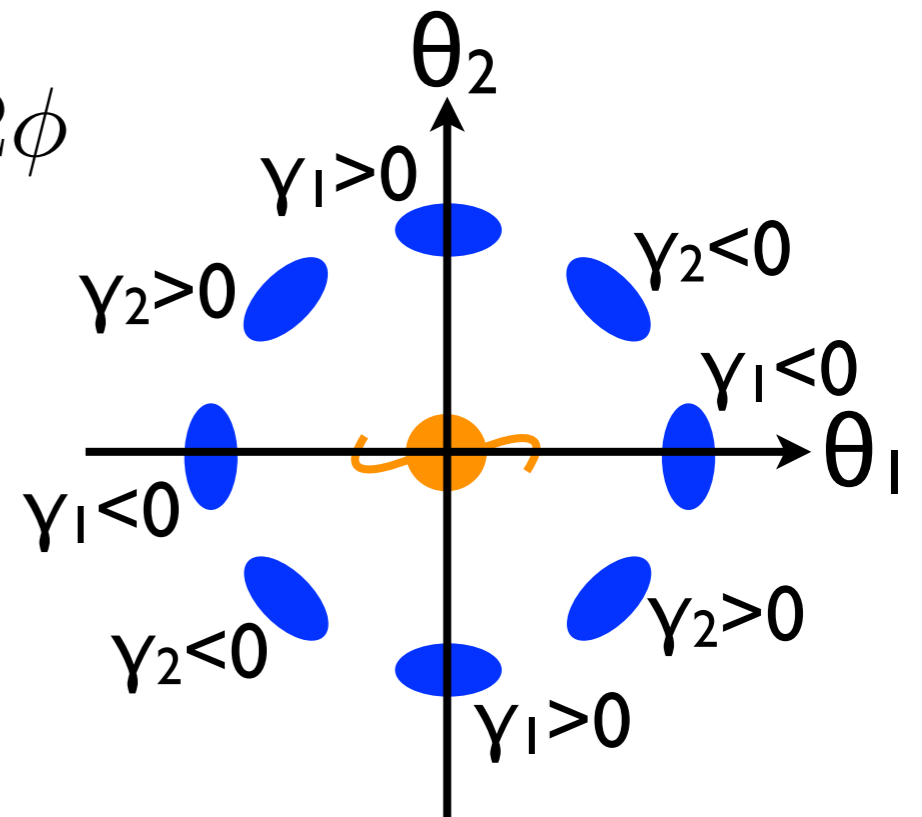
using the relation: $\bar{\kappa}'(< \theta) = -\frac{2}{\theta} [\bar{\kappa}(< \theta) - \kappa(\theta)]$

$$\gamma_1 = \frac{1}{2} \left(\frac{\partial \alpha_1}{\partial \theta_1} - \frac{\partial \alpha_2}{\partial \theta_2} \right) = - [\bar{\kappa}(< \theta) - \kappa(\theta)] \cos 2\phi$$

$$\gamma_2 = \frac{\partial \alpha_1}{\partial \theta_2} = - [\bar{\kappa}(< \theta) - \kappa(\theta)] \sin 2\phi$$

lens object centered at $\theta \approx 0$

$$\rightarrow \bar{\kappa}(< \theta) - \kappa(\theta) > 0$$



Circular symmetric lenses (V)

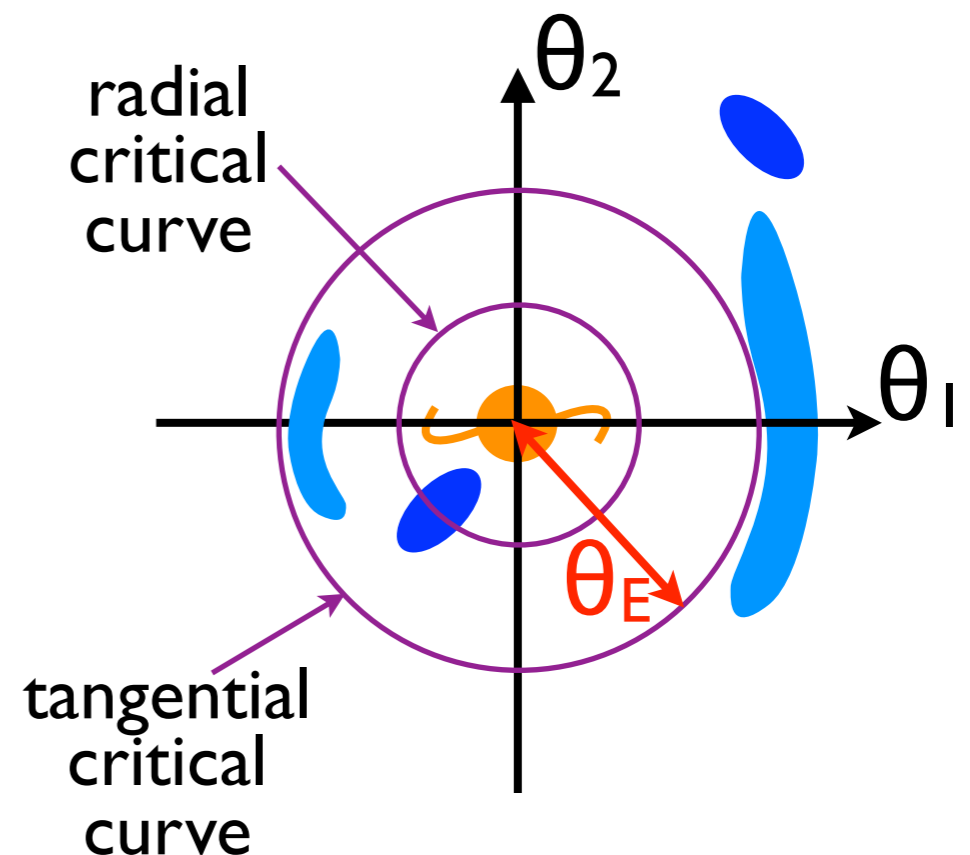
- critical curves

$$\det A = (1 - \kappa)^2 - |\gamma|^2 = \underbrace{[1 - \bar{\kappa}(< \theta)]}_{\text{tangential critical curve}} \underbrace{[1 + \bar{\kappa}(< \theta) - 2\kappa(\theta)]}_{\text{radial critical curve}}$$

tangential critical curve
is a solution for $\beta=0$

$$\bar{\kappa}(< \theta_E) = 1$$

θ_E : Einstein radius

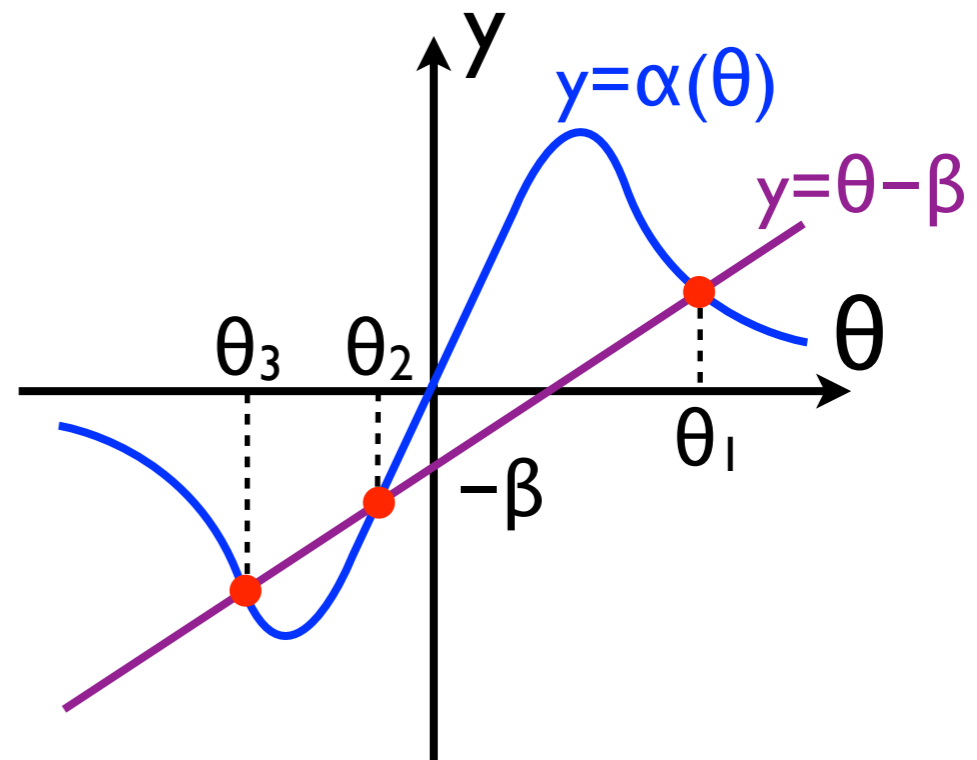


Solutions of lens equation

- lens equation is 1D equation
- ‘diagrammatic’ approach is useful to understand how multiple solutions appear

$$\beta = \theta - \alpha(\theta)$$

$$\Leftrightarrow \begin{cases} y = \alpha(\theta) \\ y = \theta - \beta \end{cases}$$



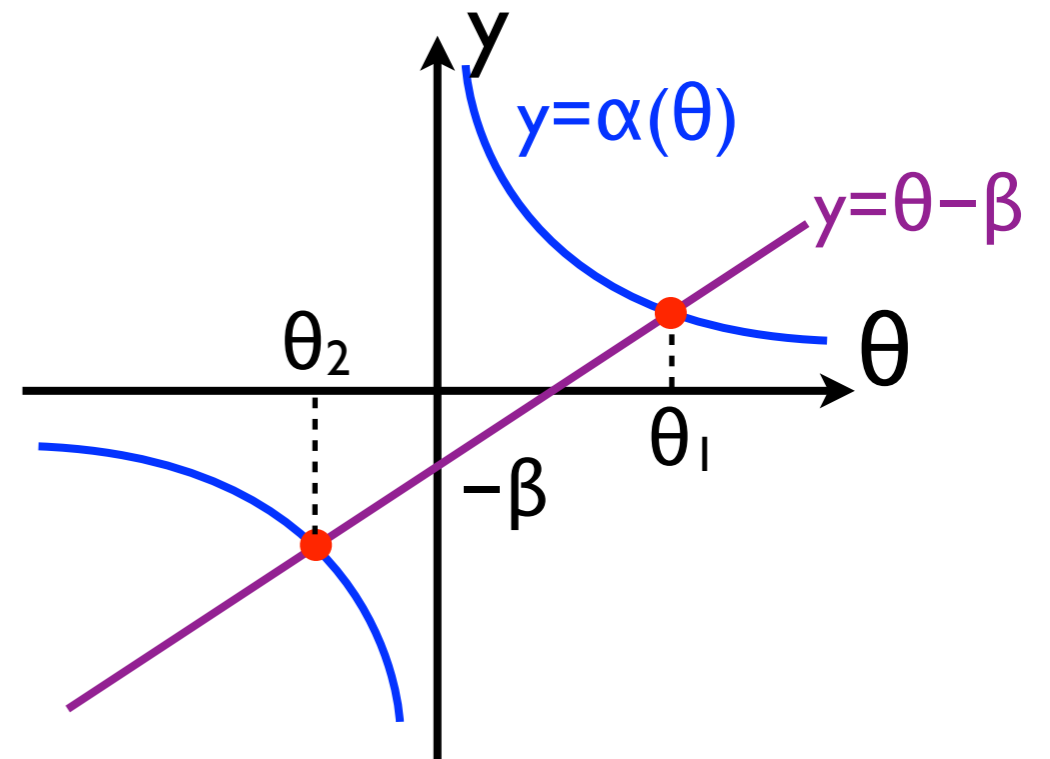
Example 1: point mass

- model for stars, compact galaxies, ...

$$\bar{\kappa}(< \theta) = \frac{M}{\pi D_A^2(z_l) \Sigma_{\text{cr}}} \frac{1}{\theta^2} = \frac{\theta_E^2}{\theta^2}$$
$$\equiv \theta_E^2$$

$$\alpha(\theta) = \theta \bar{\kappa}(< \theta) \propto \frac{1}{\theta}$$

always two images



Example 2: singular isothermal sphere

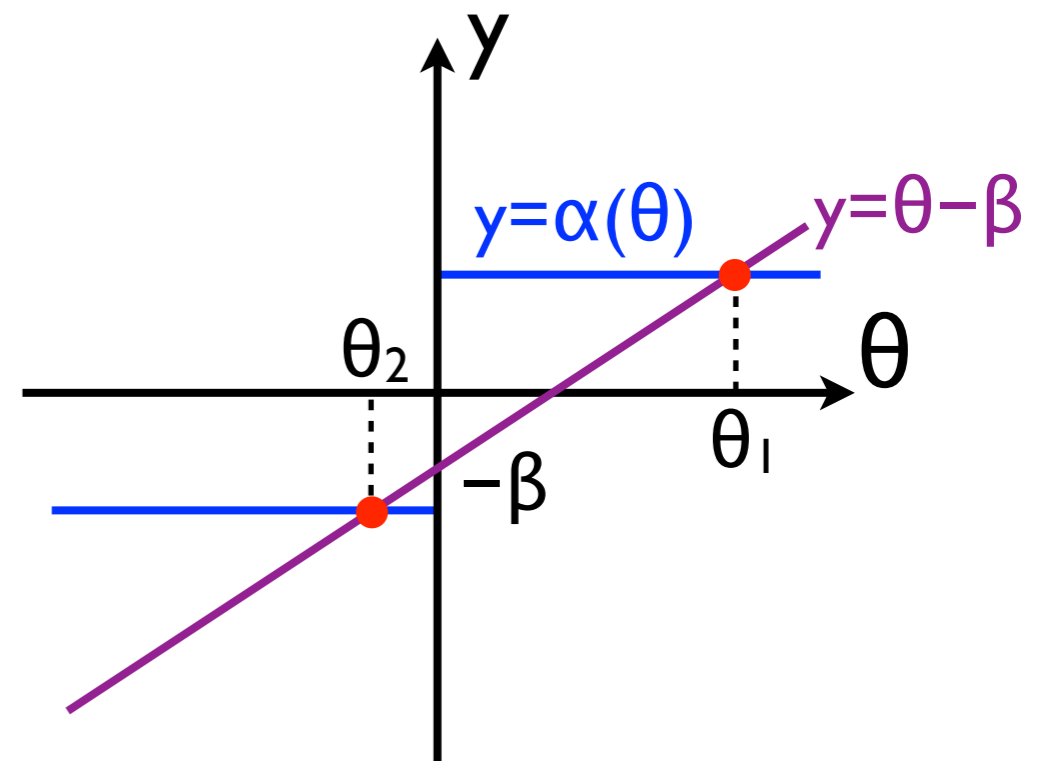
- standard lens model for galaxies

$$\rho(r) = \frac{\sigma^2}{2\pi G r^2} \quad \Sigma(x) = \frac{\sigma^2}{2\pi G} \int_{-\infty}^{\infty} \frac{dz}{x^2 + z^2} = \frac{\sigma^2}{2GD_A(z_l)\theta}$$

$$\kappa(\theta) = 2\pi \left(\frac{\sigma}{c}\right)^2 \frac{D_A(z_l, z_s)}{D_A(z_s)} \frac{1}{\theta}$$

$$\bar{\kappa}(< \theta) = 4\pi \left(\frac{\sigma}{c}\right)^2 \frac{D_A(z_l, z_s)}{D_A(z_s)} \frac{1}{\theta} = \frac{\theta_E}{\theta}$$

$\equiv \theta_E$



two images when $|\beta| < \theta_E$
 one image when $|\beta| > \theta_E$

Example 3: NFW profile

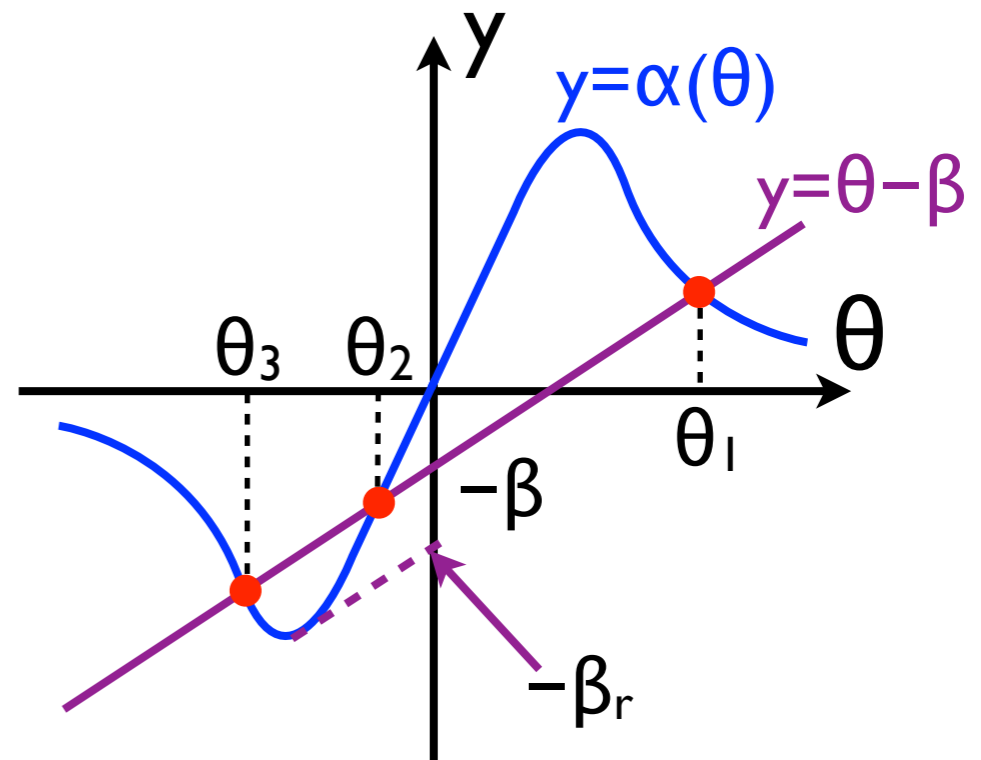
- standard lens model for dark matter halos

$$\rho(r) = \frac{\rho_s}{(r/r_s)(1 + r/r_s)^2}$$

$$\bar{\kappa}(< \theta) \propto \begin{cases} \ln(\theta_s/\theta) & (\theta \ll \theta_s) \\ \theta^{-2} & (\theta \gg \theta_s) \end{cases}$$

$$\alpha(\theta) \propto \begin{cases} \theta \ln(\theta_s/\theta) & (\theta \ll \theta_s) \\ \theta^{-1} & (\theta \gg \theta_s) \end{cases}$$

three images when $|\beta| < \beta_r$
 one image when $|\beta| > \beta_r$



More realistic models (I)

- elliptical lens $\theta \rightarrow u \equiv \sqrt{\frac{\theta_1^2}{1-e} + (1-e)\theta_2^2}$

two approaches:

1. elliptical density $\kappa(u)$

$\kappa(u) \rightarrow \psi(\vec{\theta}), \vec{\alpha}(\vec{\theta}), \dots$ through 1D integral
computationally more expensive

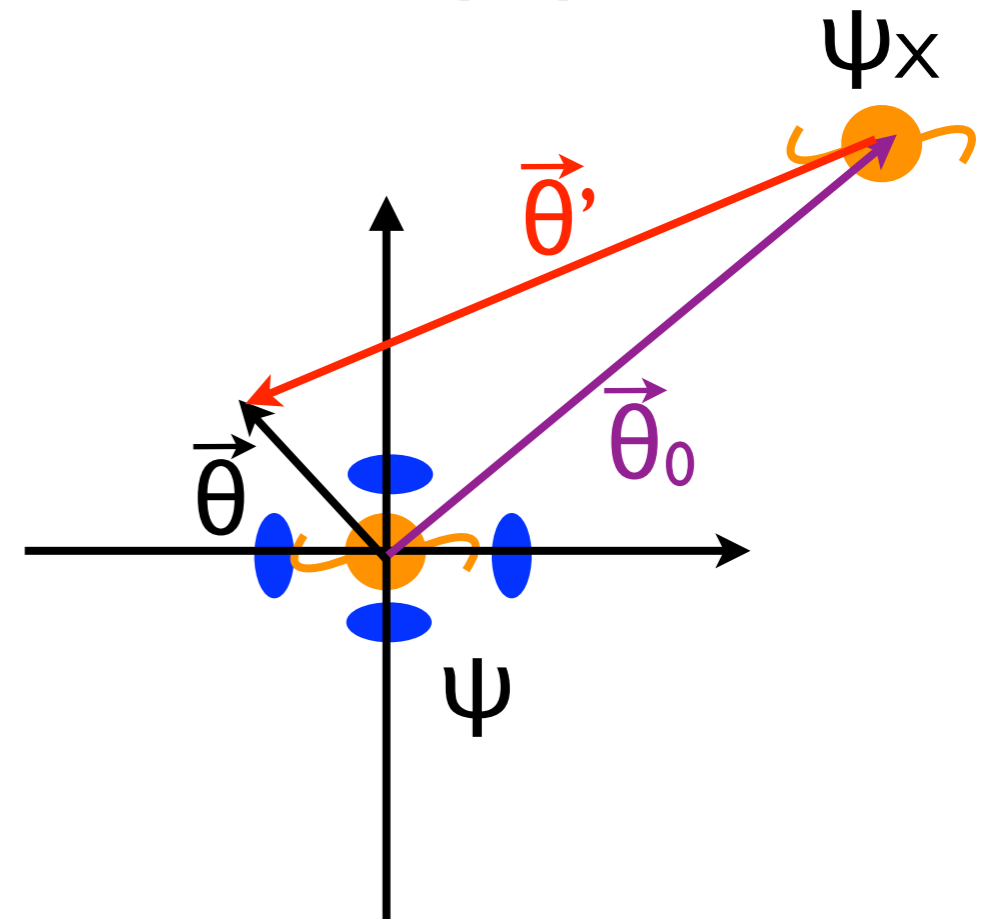
2. elliptical potential $\psi(u)$

can use circular sym. result, much easier,
but can cause unphysical mass distributions
(‘dumbbell’-like κ map, negative κ ,)

More realistic models (II)

- external perturbation

nearby object (X)
also contributes to
the lens potential



$$\psi_X(\vec{\theta}') = \psi_X(\vec{\theta} - \vec{\theta}_0)$$

$$\approx \underbrace{\psi_X(-\vec{\theta}_0)}_{\text{constant}} + \underbrace{\vec{\theta} \cdot \left. \frac{\partial \psi_X}{\partial \vec{\theta}} \right|_{-\vec{\theta}_0}}_{\text{uniform } \vec{\alpha}} + \frac{1}{2} \vec{\theta} \cdot \underbrace{H[\psi_X(-\vec{\theta}_0)]}_{\text{Hessian matrix}} \cdot \vec{\theta} + \dots$$

$$H[\psi(\theta)] = \begin{pmatrix} \psi_{11} & \psi_{12} \\ \psi_{21} & \psi_{22} \end{pmatrix} = \begin{pmatrix} \kappa + \gamma_1 & \gamma_2 \\ \gamma_2 & \kappa - \gamma_1 \end{pmatrix}$$

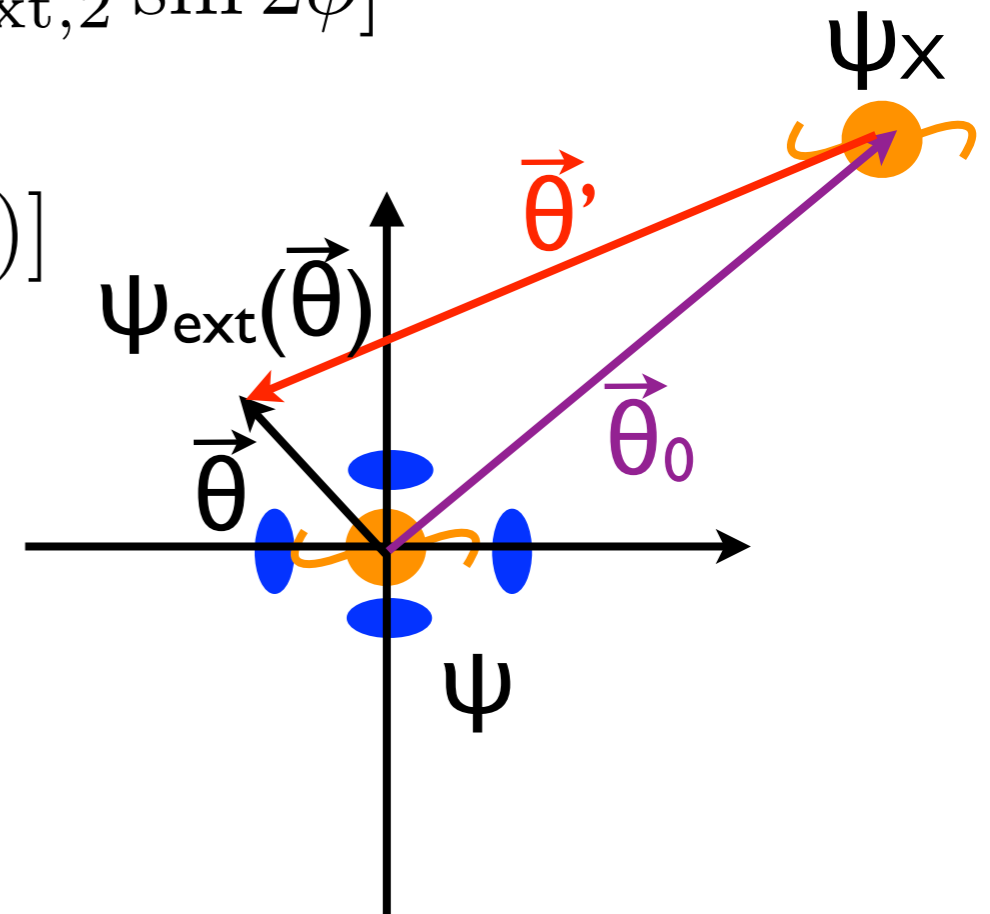
More realistic models (III)

- therefore, the effect of X on the main lens potential at $\vec{\theta}$, $\psi_{\text{ext}}(\vec{\theta}) = \psi_X(\vec{\theta}')$, becomes

[again, polar coords $(\theta_1, \theta_2) = (\theta \cos \phi, \theta \sin \phi)$]

$$\begin{aligned} \psi_{\text{ext}}(\vec{\theta}) &\approx \frac{\theta^2}{2} [\kappa_{\text{ext}} + \gamma_{\text{ext},1} \cos 2\phi + \gamma_{\text{ext},2} \sin 2\phi] \\ &\approx \frac{\theta^2}{2} [\kappa_{\text{ext}} + \gamma_{\text{ext}} \cos 2(\phi - \phi_0)] \end{aligned}$$

(ϕ_0 : polar angle corresponds to the direction to perturber)



Numerical approach

- recall: solving lens equation is hard in general

$$\vec{\beta} = \vec{\theta} - \vec{\alpha}(\vec{\theta})$$

($\vec{\beta} \rightarrow \vec{\theta}$ is non-linear, multiple solutions allowed)

- numerical techniques to solve lens equation necessary

Numerical root finding

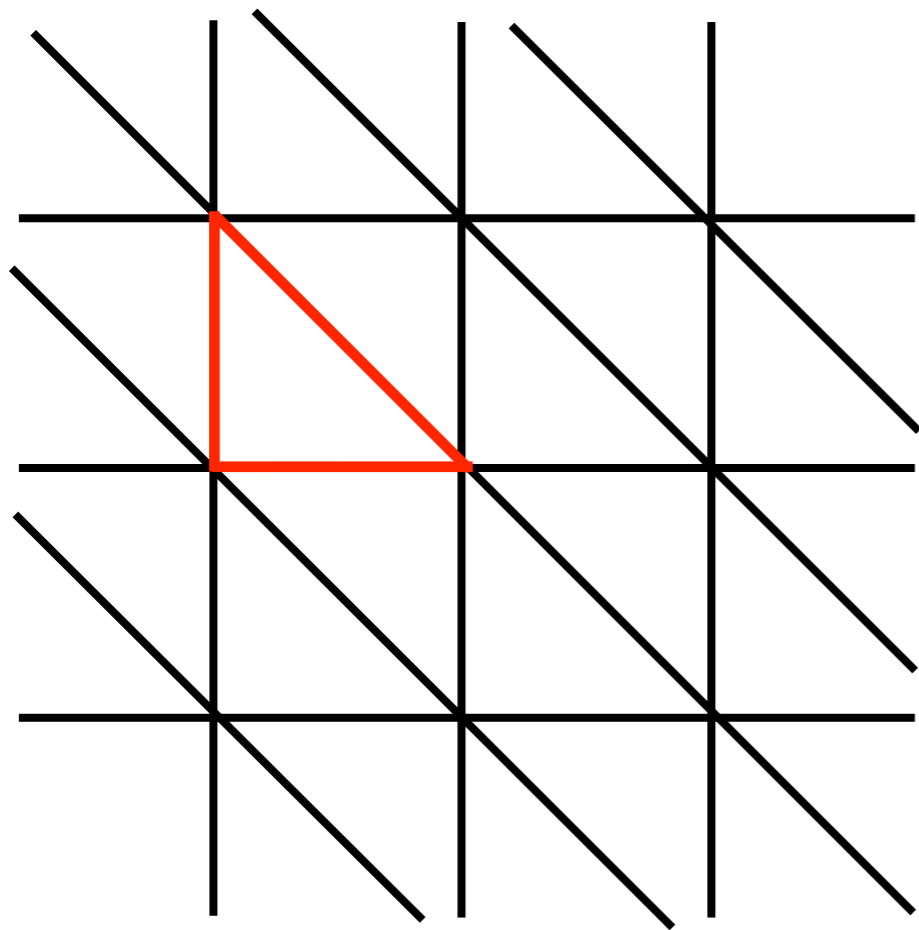
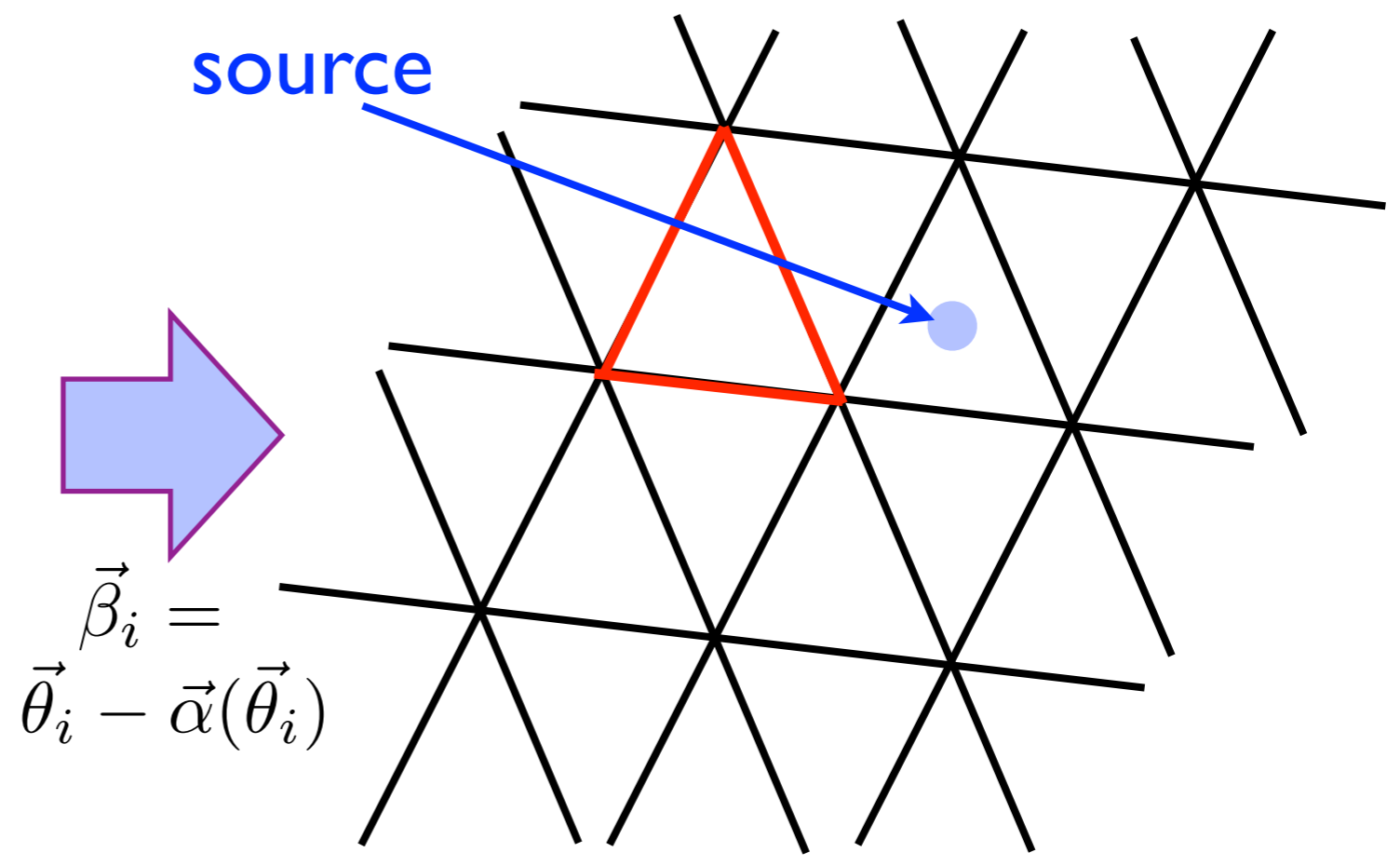


image plane ($\vec{\theta}_i$)



source plane ($\vec{\beta}_i$)

→

$$\vec{\beta}_i = \vec{\alpha}(\vec{\theta}_i)$$

Numerical root finding

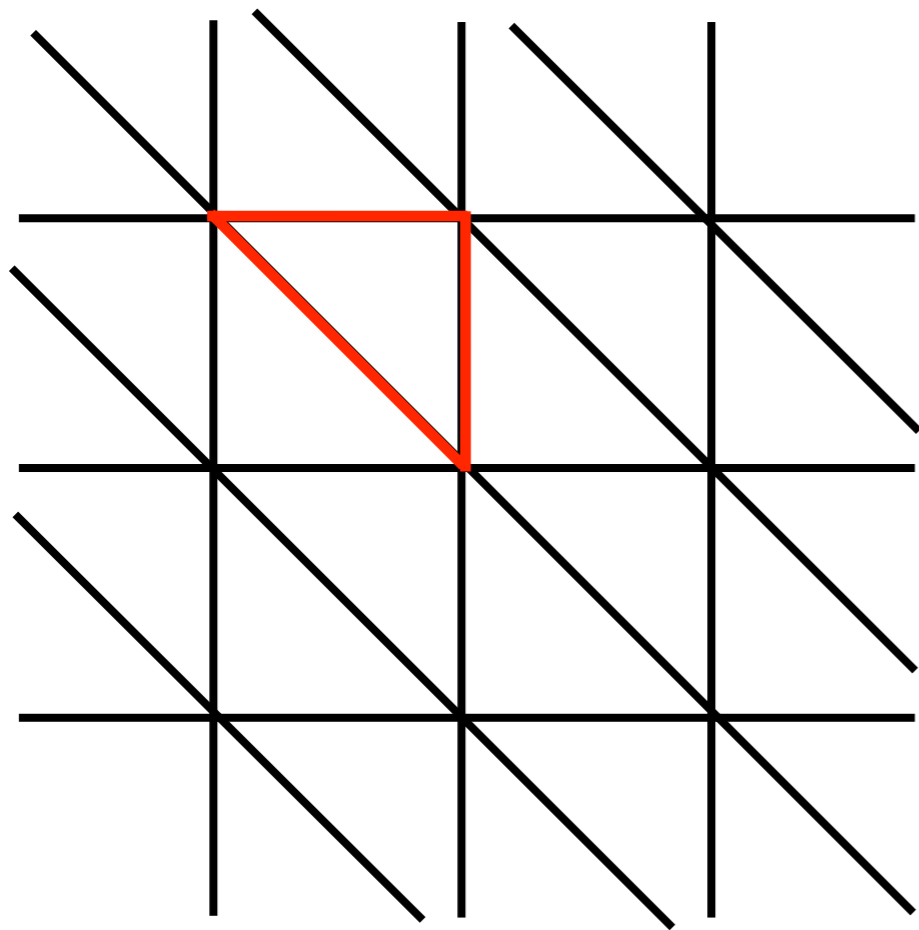
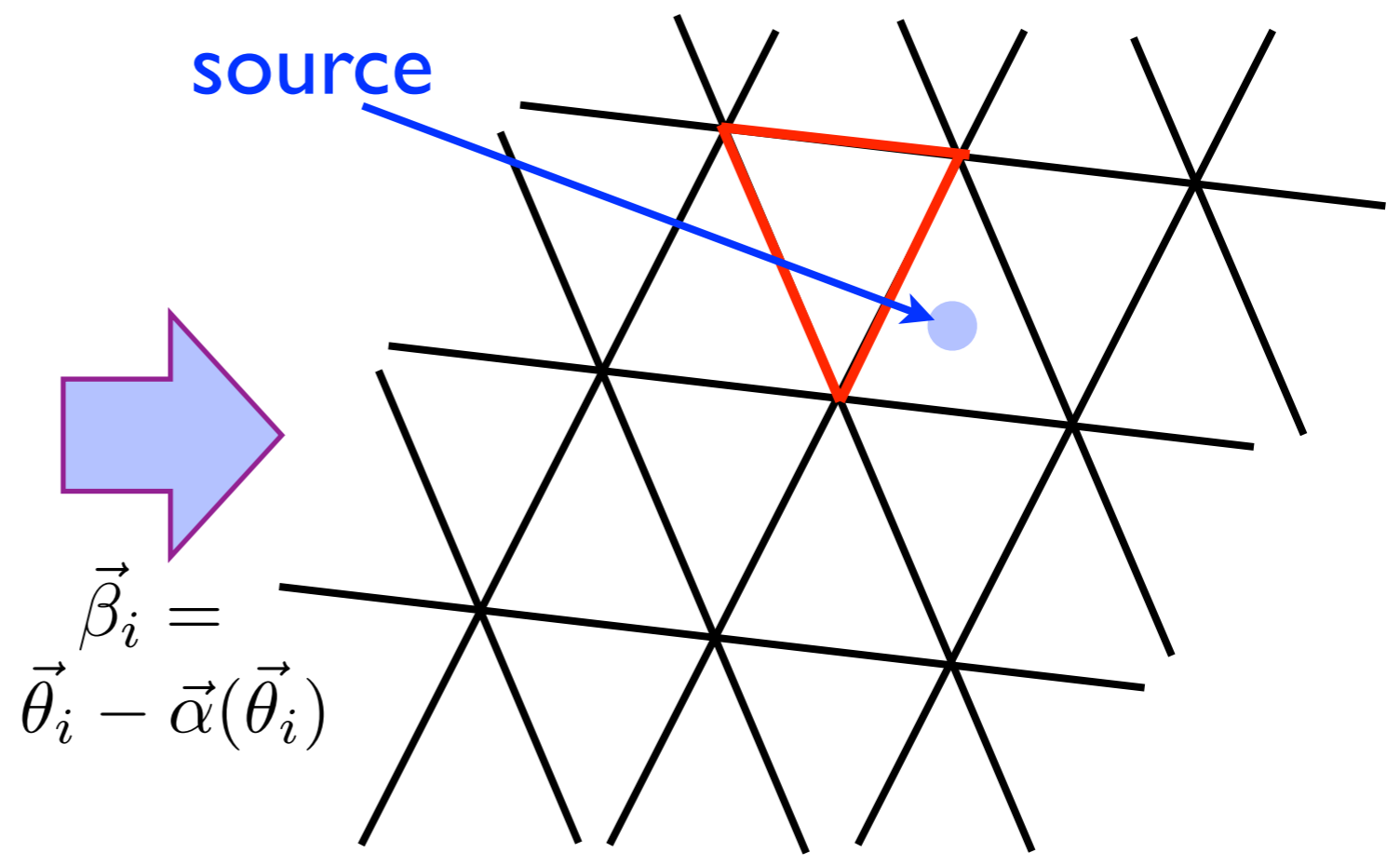


image plane ($\vec{\theta}_i$)



source plane ($\vec{\beta}_i$)

→

$$\vec{\beta}_i = \vec{\theta}_i - \vec{\alpha}(\vec{\theta}_i)$$

Numerical root finding

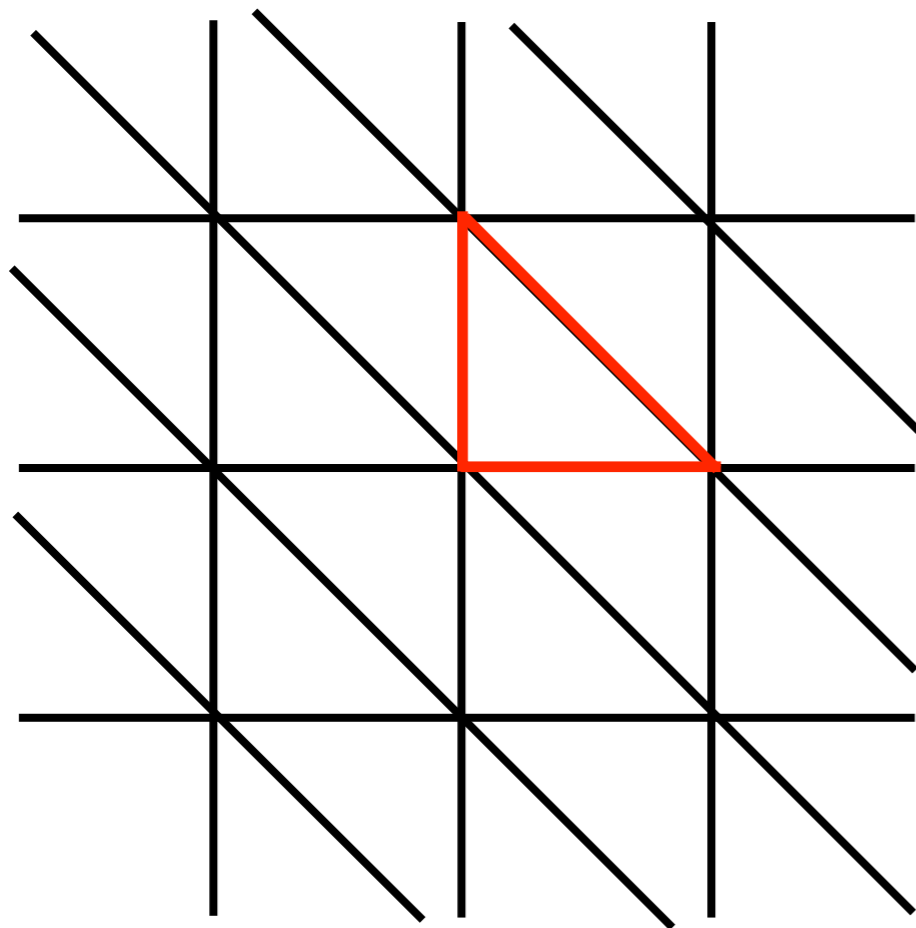
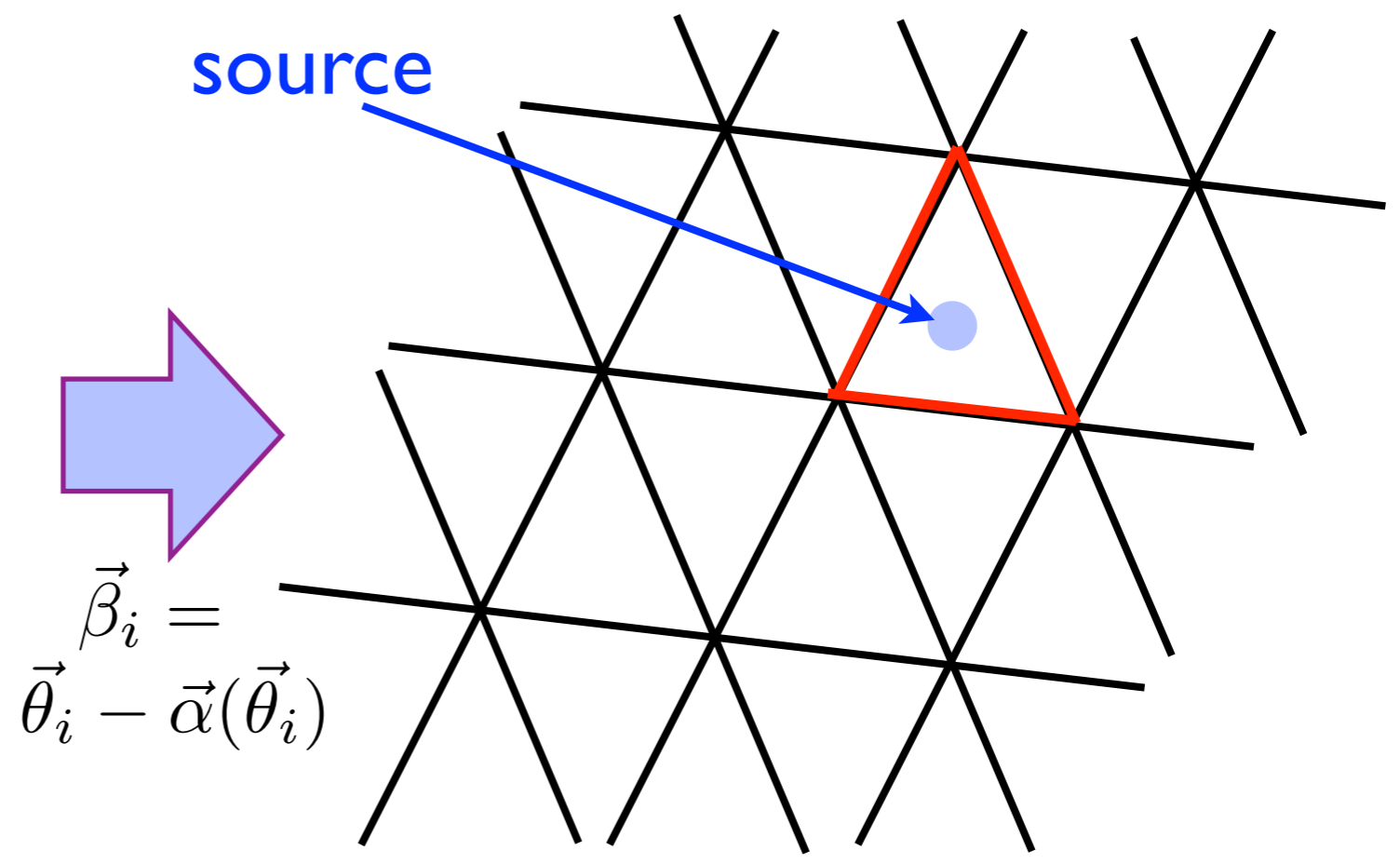


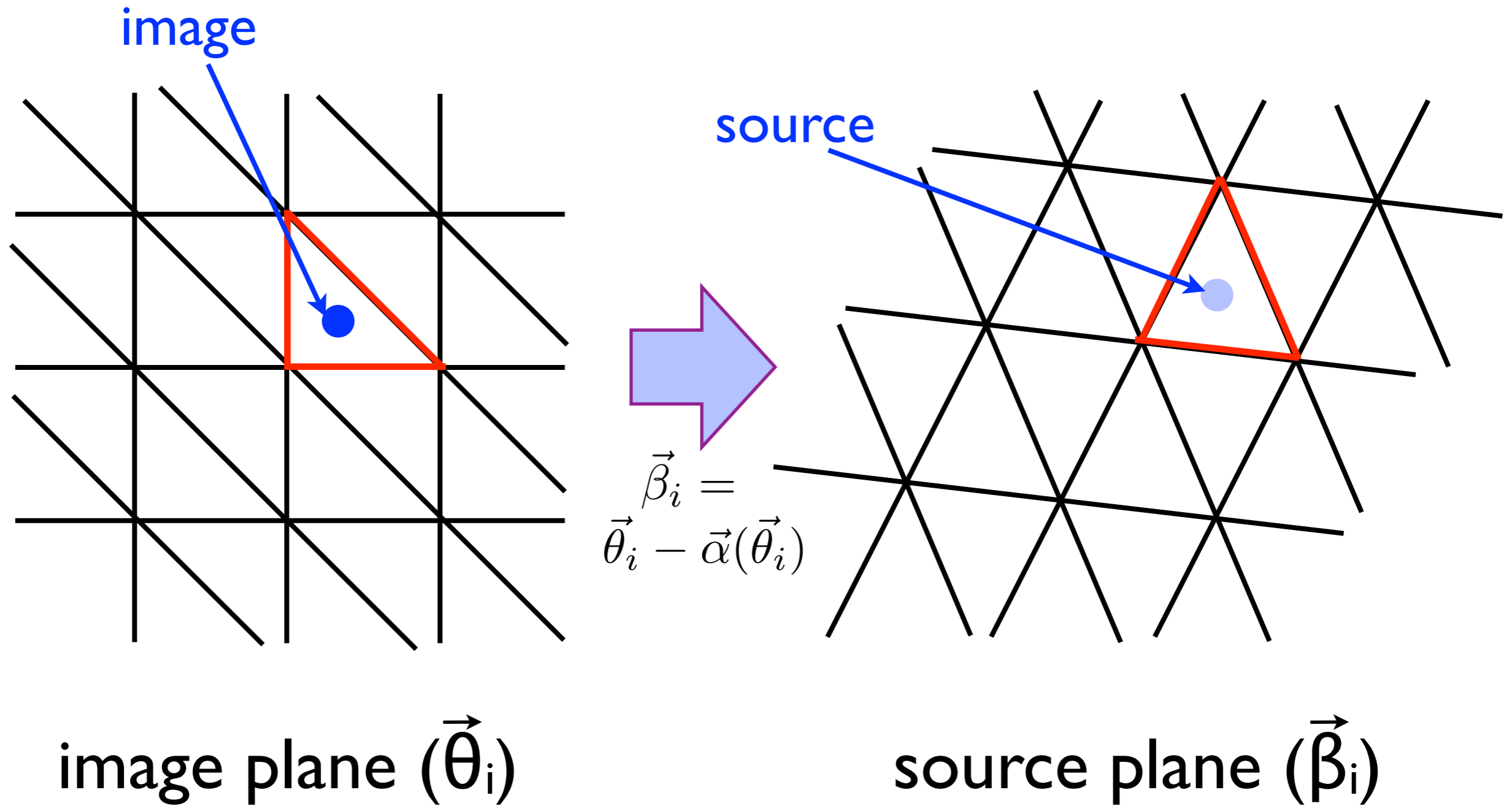
image plane ($\vec{\theta}_i$)



source plane ($\vec{\beta}_i$)

$$\vec{\beta}_i = \vec{\theta}_i - \vec{\alpha}(\vec{\theta}_i)$$

Numerical root finding



Resolution issue

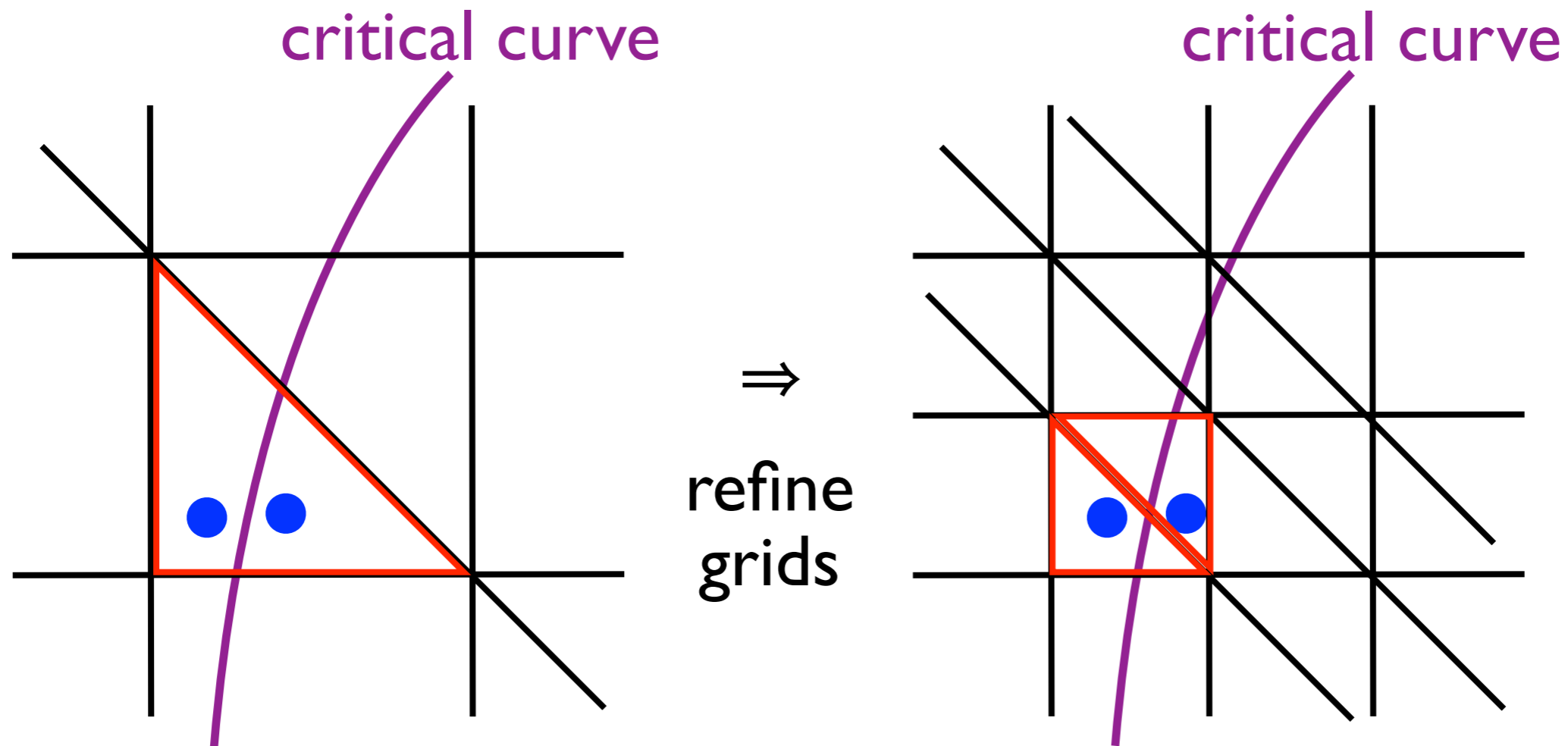


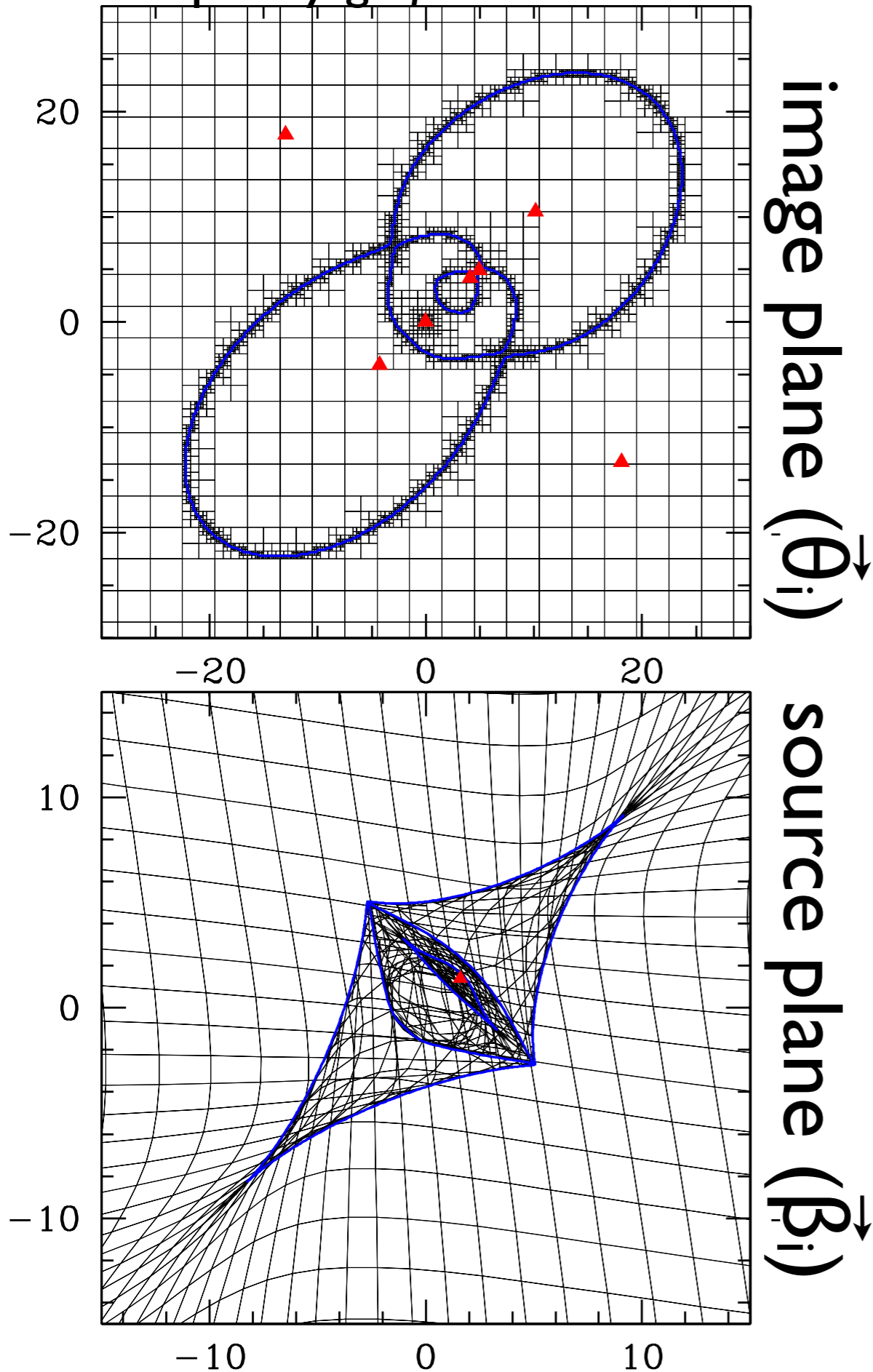
image plane ($\vec{\theta}_i$)

fail to resolve
multiple images

image plane ($\vec{\theta}_i$)

multiple images
resolved

example by *glafic*



Practical cases

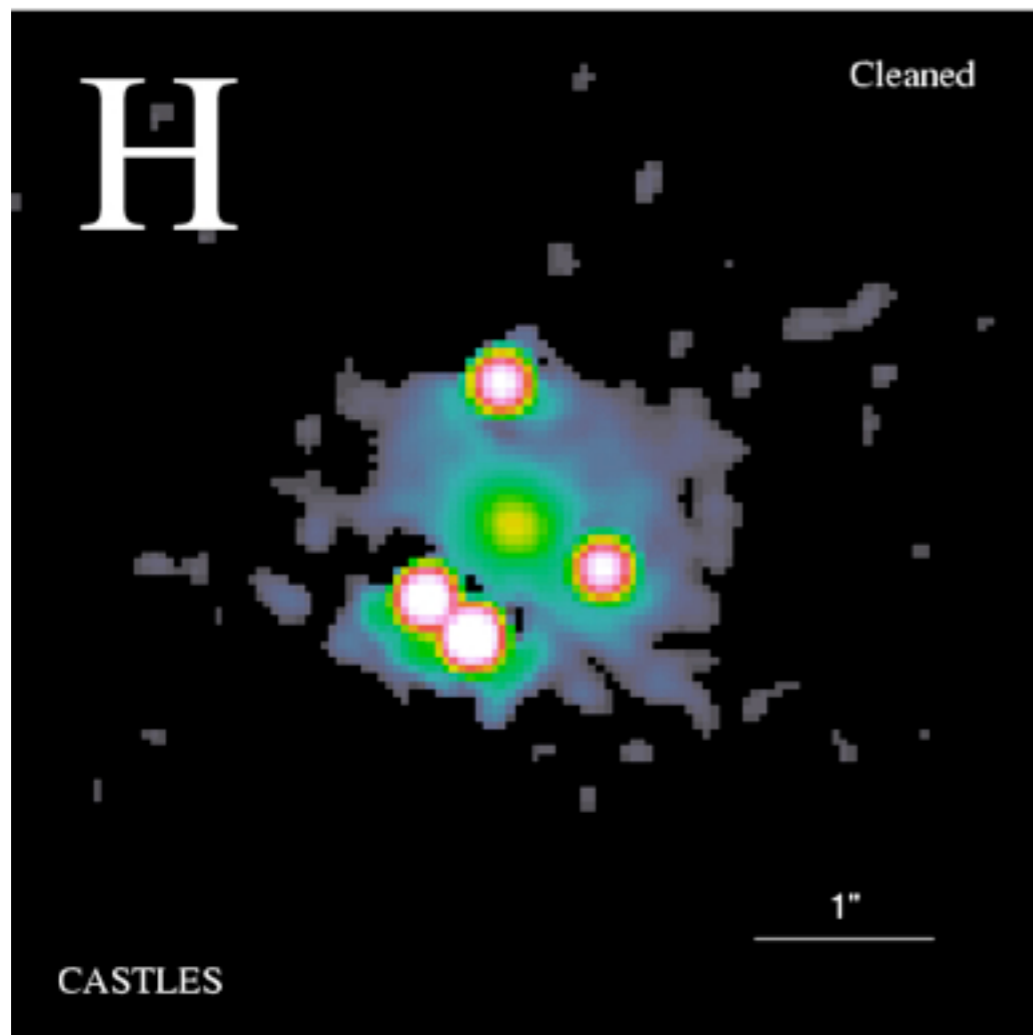
- very high grid resolution needed only near critical curves
- **adaptive grid** for efficient lens equation solving
- left example successfully identifies 7 lensed images of a single source

Public lens softwares

- public softwares that implement adaptive grid:
 - *glafic* (M. Oguri)
<http://www.slac.stanford.edu/~oguri/glafic/>
 - *GRAVLENS* (C. R. Keeton)
<http://redfive.physics.rutgers.edu/~keeton/gravlens/>
 - *LENSTOOL* (E. Jullo, J.-P. Kneib, et al.)
<http://lamwvs.oamp.fr/lenstool/>
 -
- see also recent review of public softwares by Lefor et al. (arXiv:1206.4382)

Modeling strong lens systems (I)

- example: WFI2626-4536 (Morgan et al. 2004)



4 image system
source quasar at $z=2.23$
lensing galaxy at $z\sim 0.4$

(HST image from CASTLES website)

Modeling strong lens systems (II)

- assume Singular Isothermal Ellipsoid (SIE) plus external shear
- model parameters = 9
(mass, SIE centroid, e , PA_e , γ_{ext} , PA_γ , $\vec{\beta}$)
- observational constraints = 13
(image position \times 4, galaxy position, flux ratios \times 3)
- degree of freedom = $13 - 9 = 4$

Modeling strong lens systems (III)

- search a best-fit model by χ^2 minimization

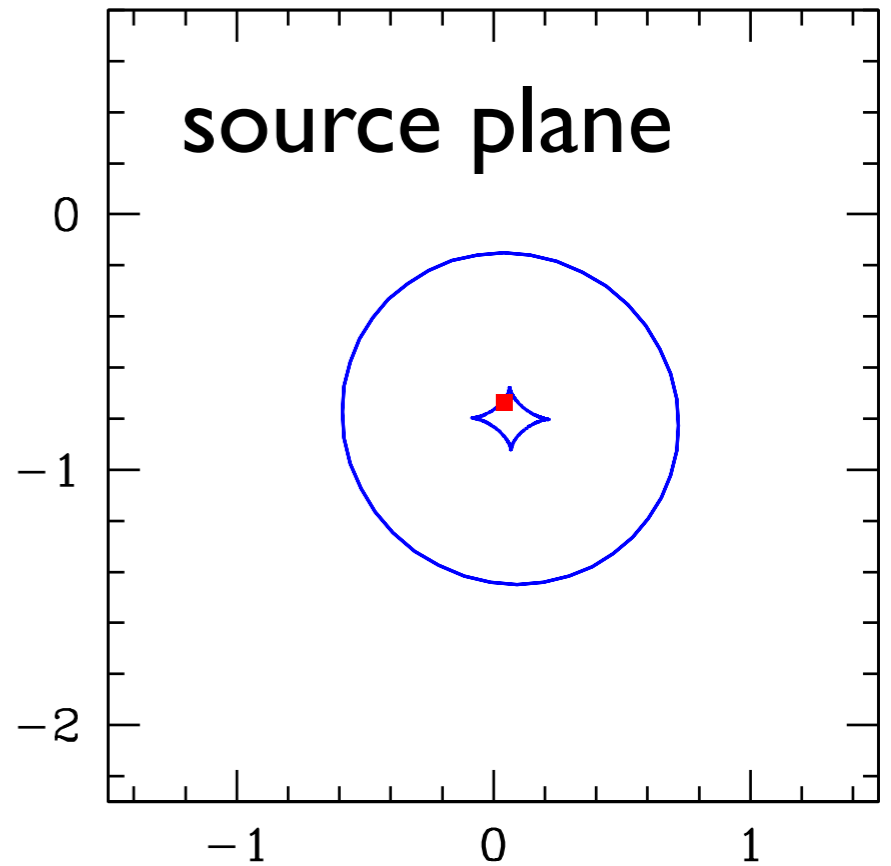
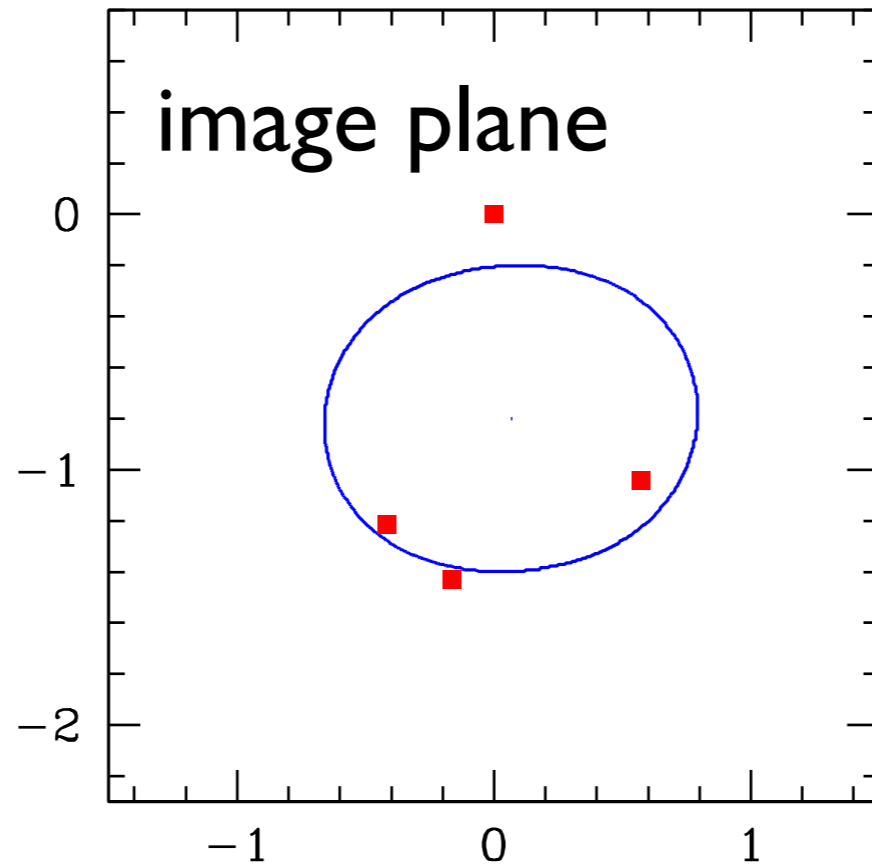
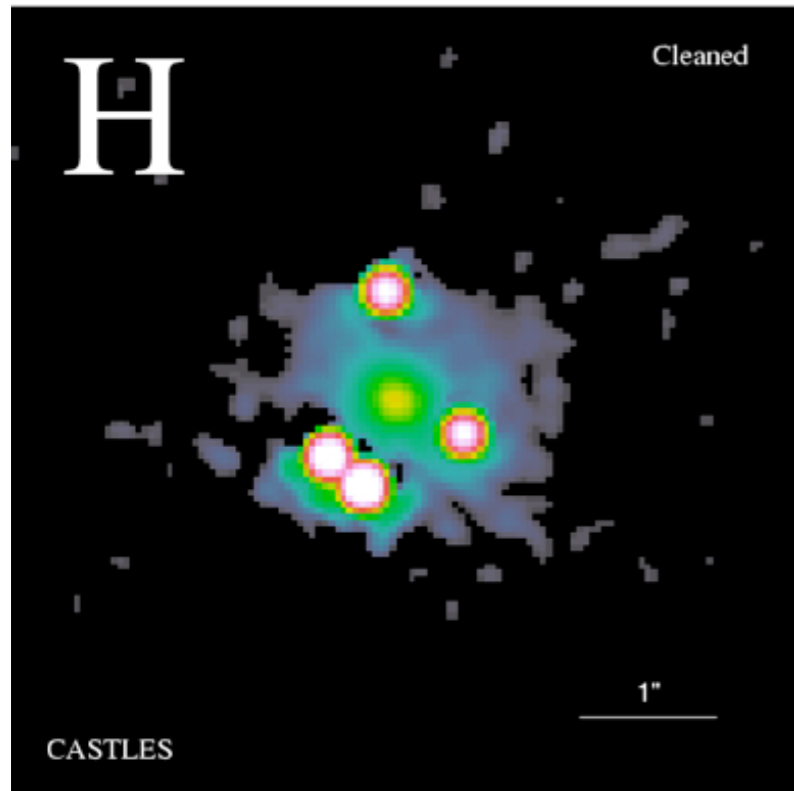
$$\chi^2 = \sum_i \frac{|\vec{\theta}_{i,\text{model}} - \vec{\theta}_{i,\text{obs}}|^2}{\sigma_{\theta_i}^2} + \sum_{ij} \frac{(\Delta m_{ij,\text{model}} - \Delta m_{ij,\text{obs}})^2}{\sigma_{\Delta m_{ij}}^2}$$

- [advanced] trick: source plane χ^2 minimization

$$\vec{\theta}_{i,\text{model}} - \vec{\theta}_{i,\text{obs}} \approx A^{-1}(\vec{\theta}_{i,\text{obs}}) \left[\vec{\beta}_{\text{model}} - \vec{\beta}(\vec{\theta}_{i,\text{obs}}) \right]$$

computation much faster, but # of images can be wrong (need cross-check)

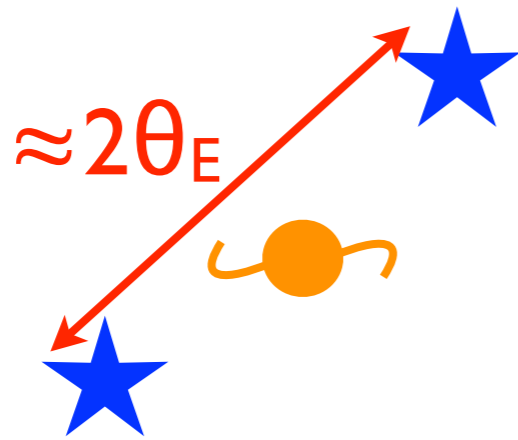
Modeling strong lens systems (IV)



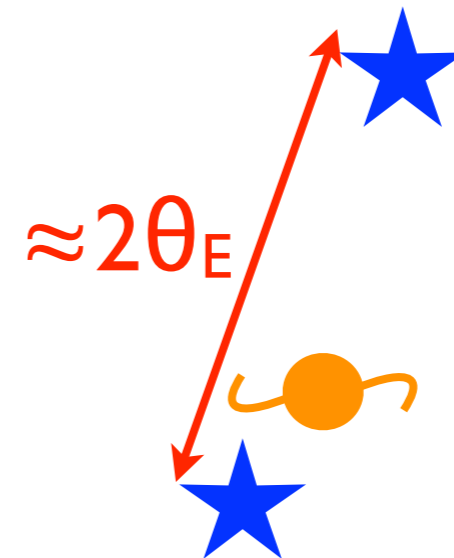
- result obtained using *glafic*
- best-fit model has $\chi^2/\text{d.o.f} = 6.4/4$

What does strong lens measure? (I)

- angular separation between images $\approx 2\theta_E$



‘symmetric’
configuration



‘asymmetric’
configuration

- therefore, multiple images provides good measurements of the Einstein radius θ_E

Image separation and Einstein radius

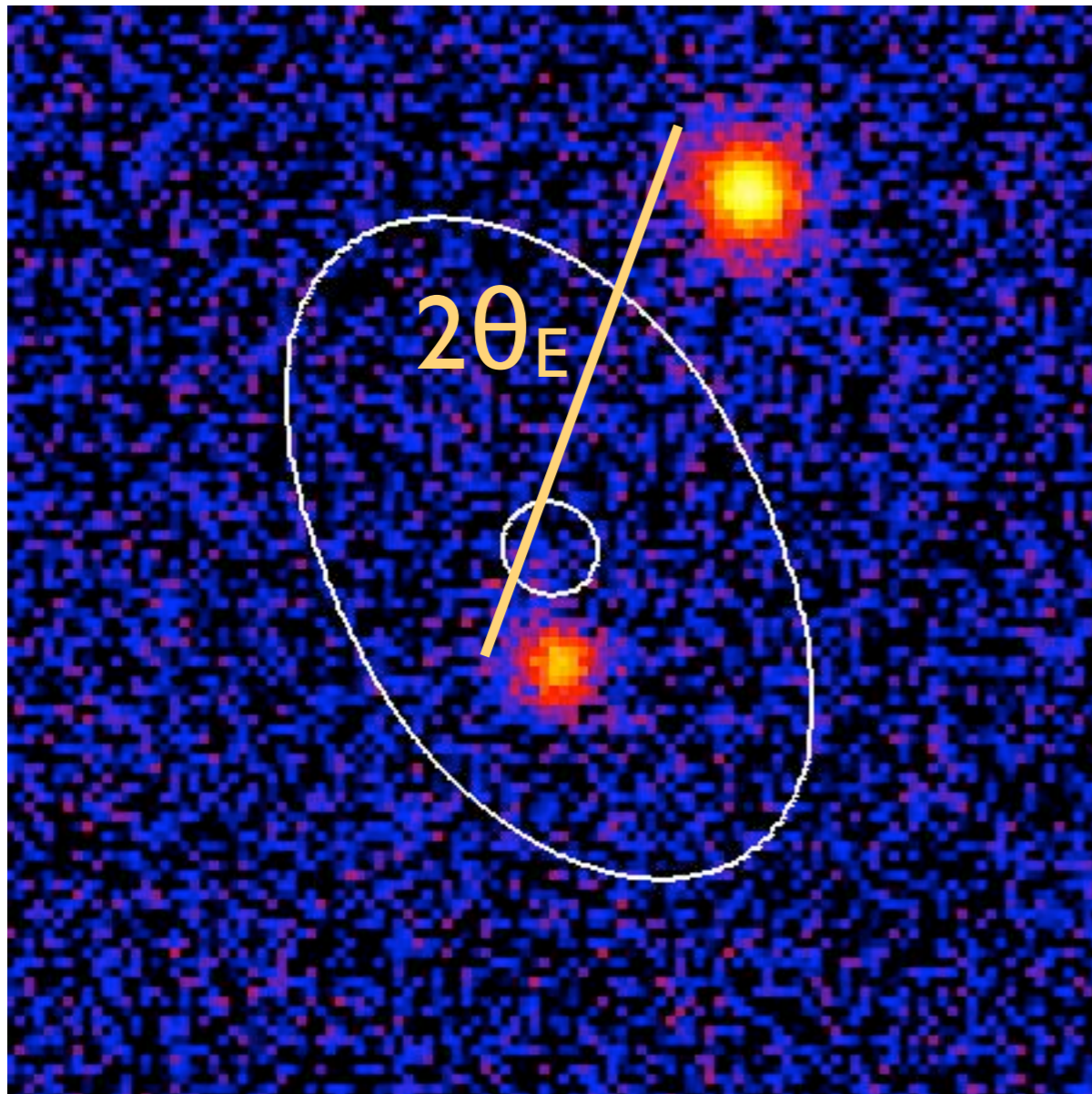
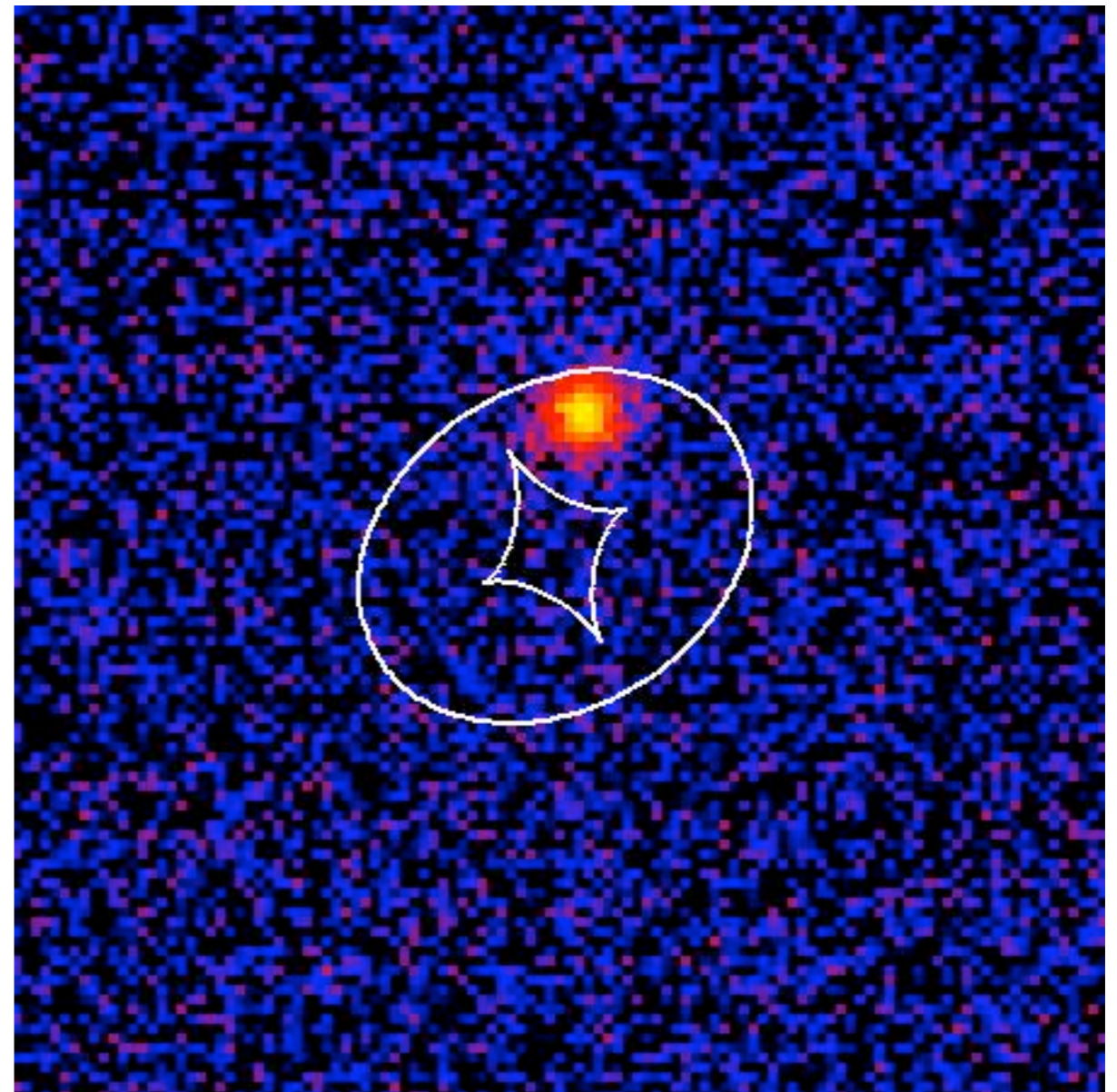


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

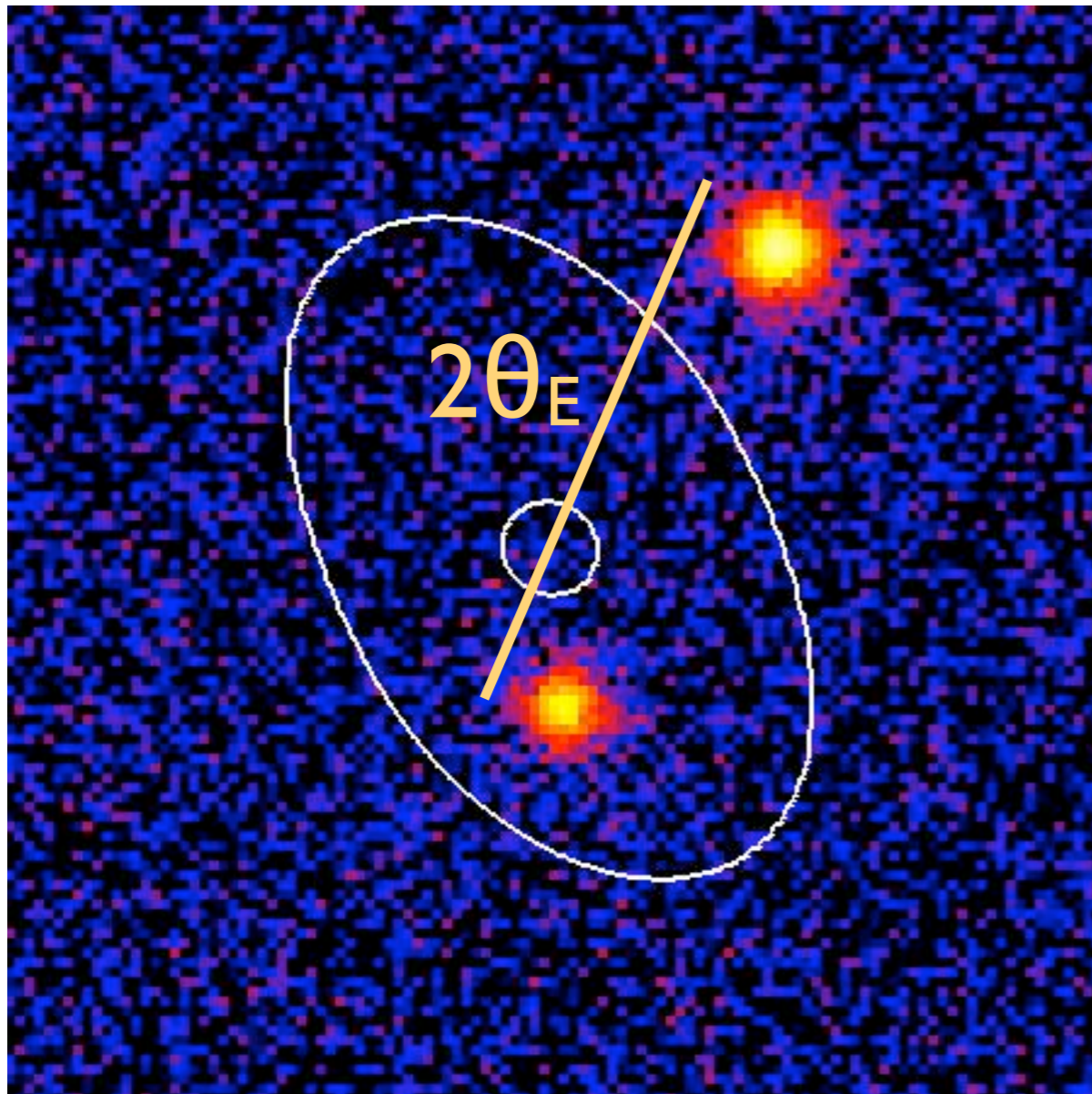
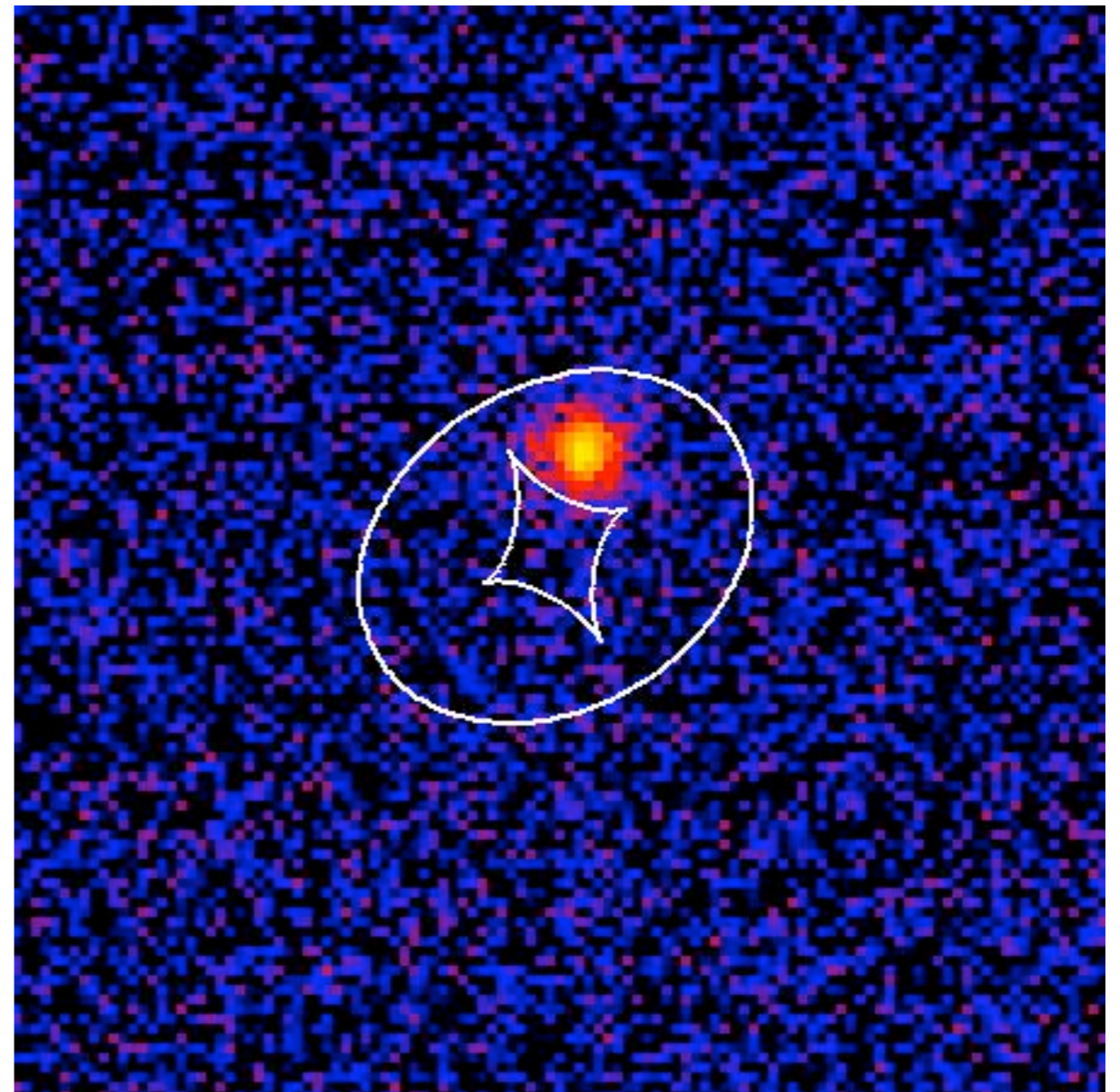


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

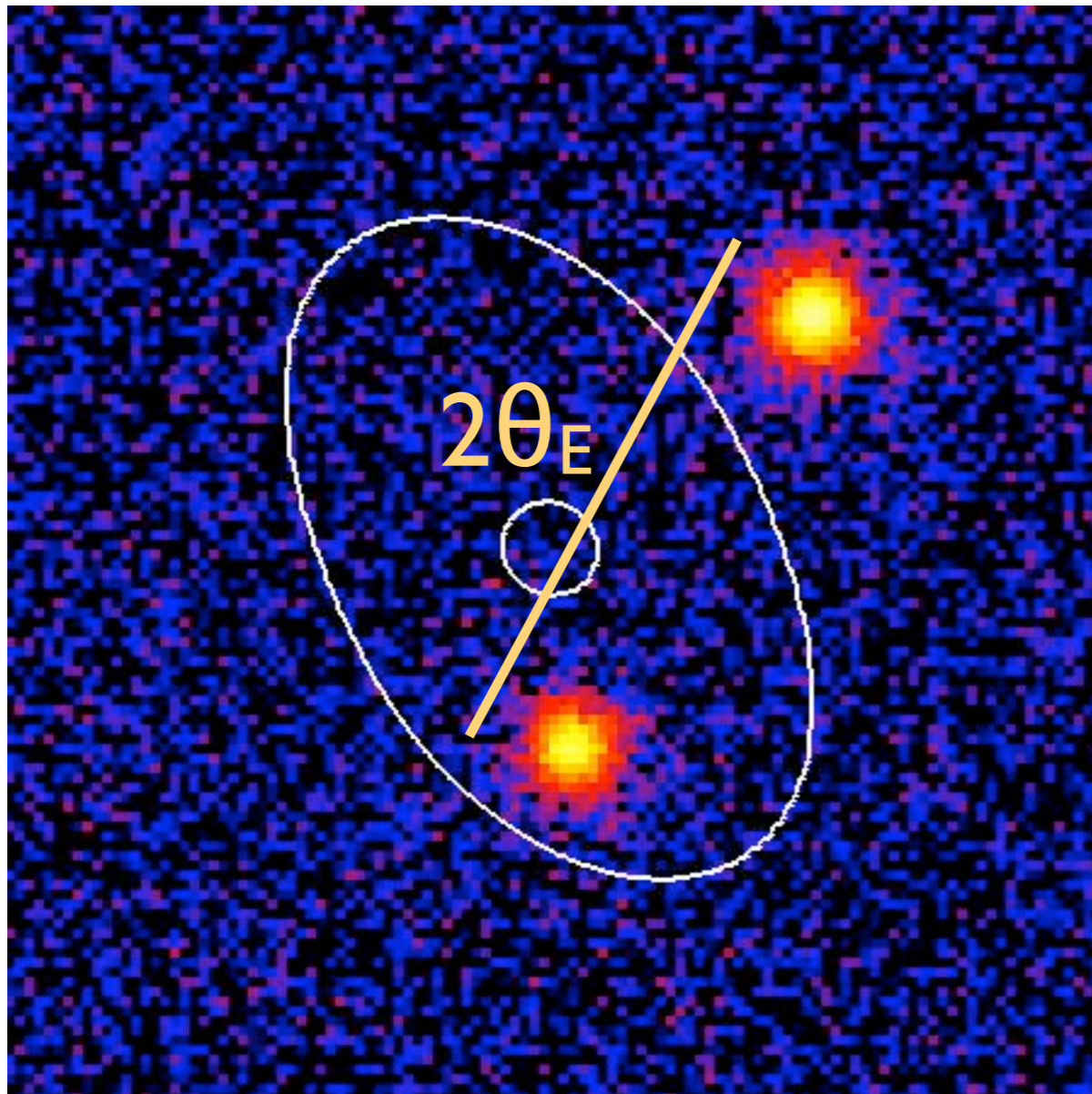
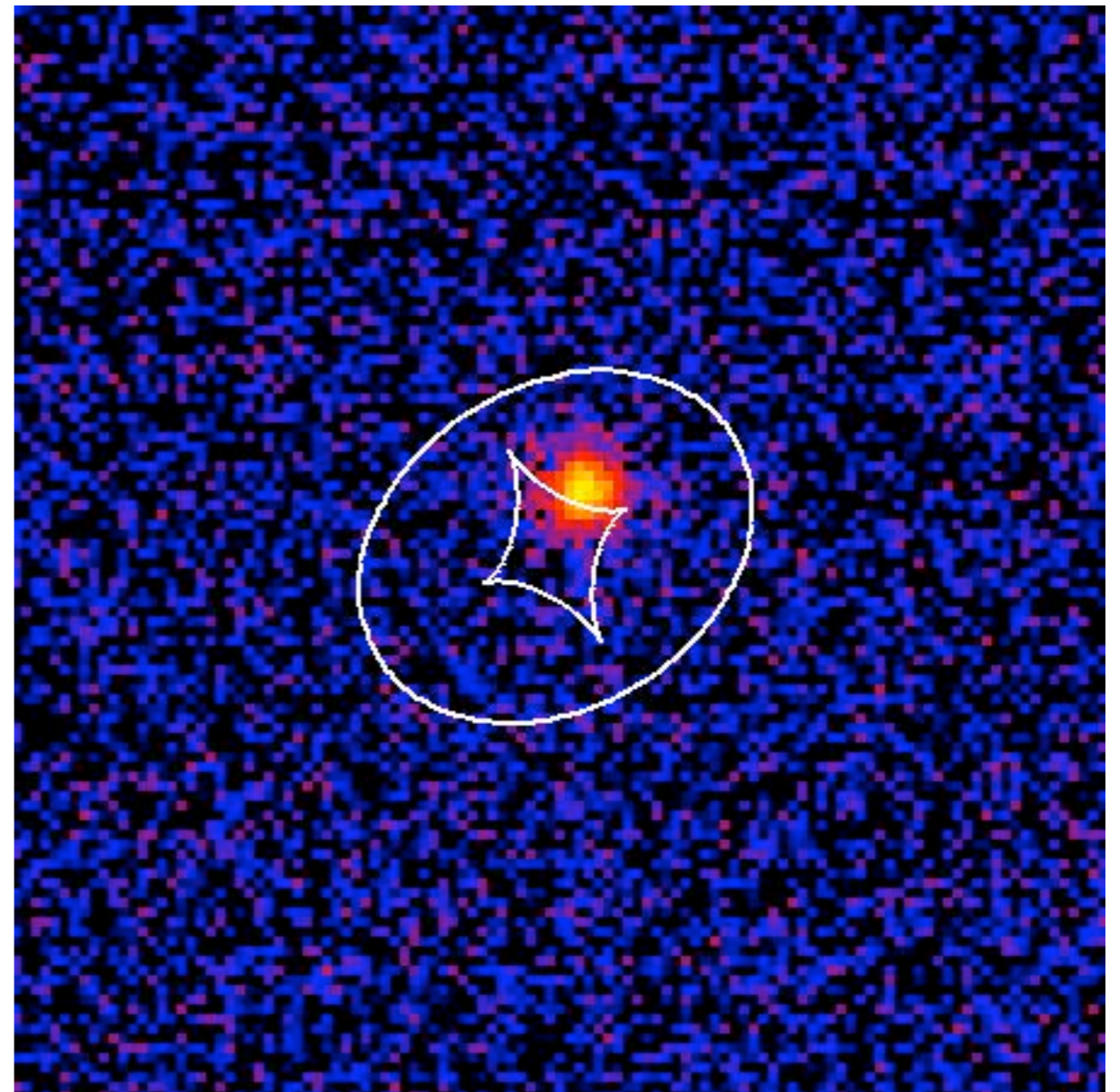


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

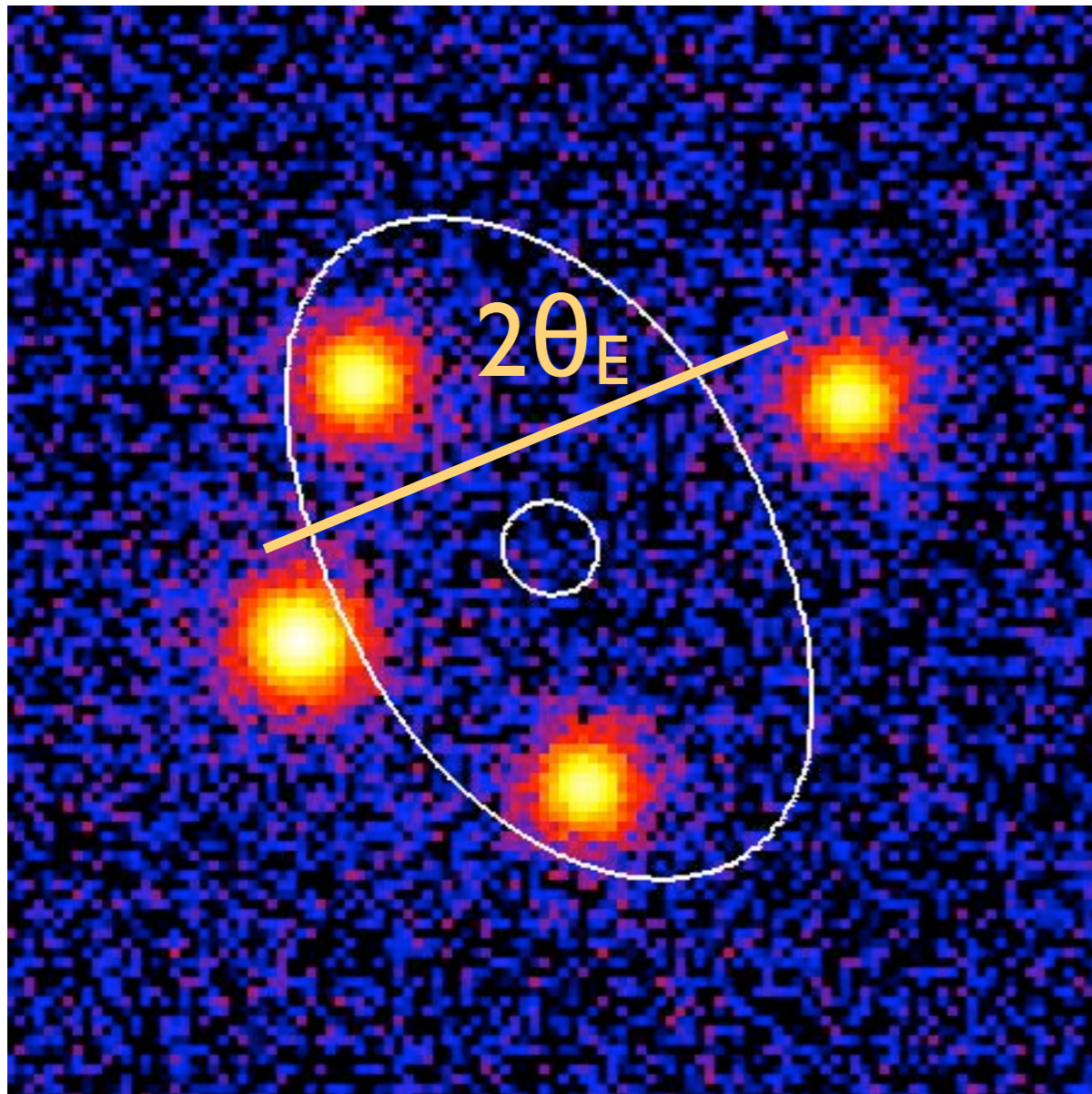
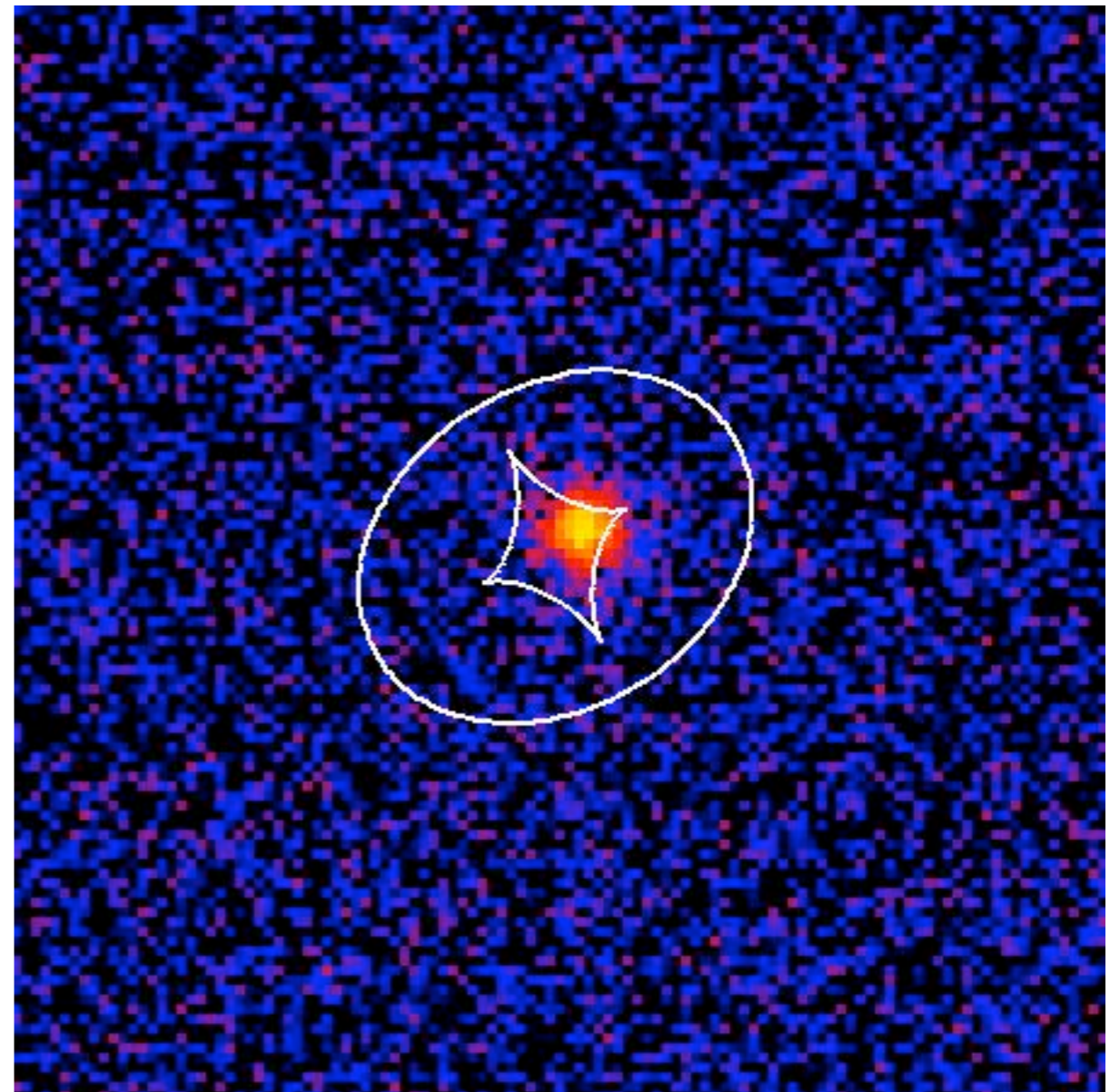


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

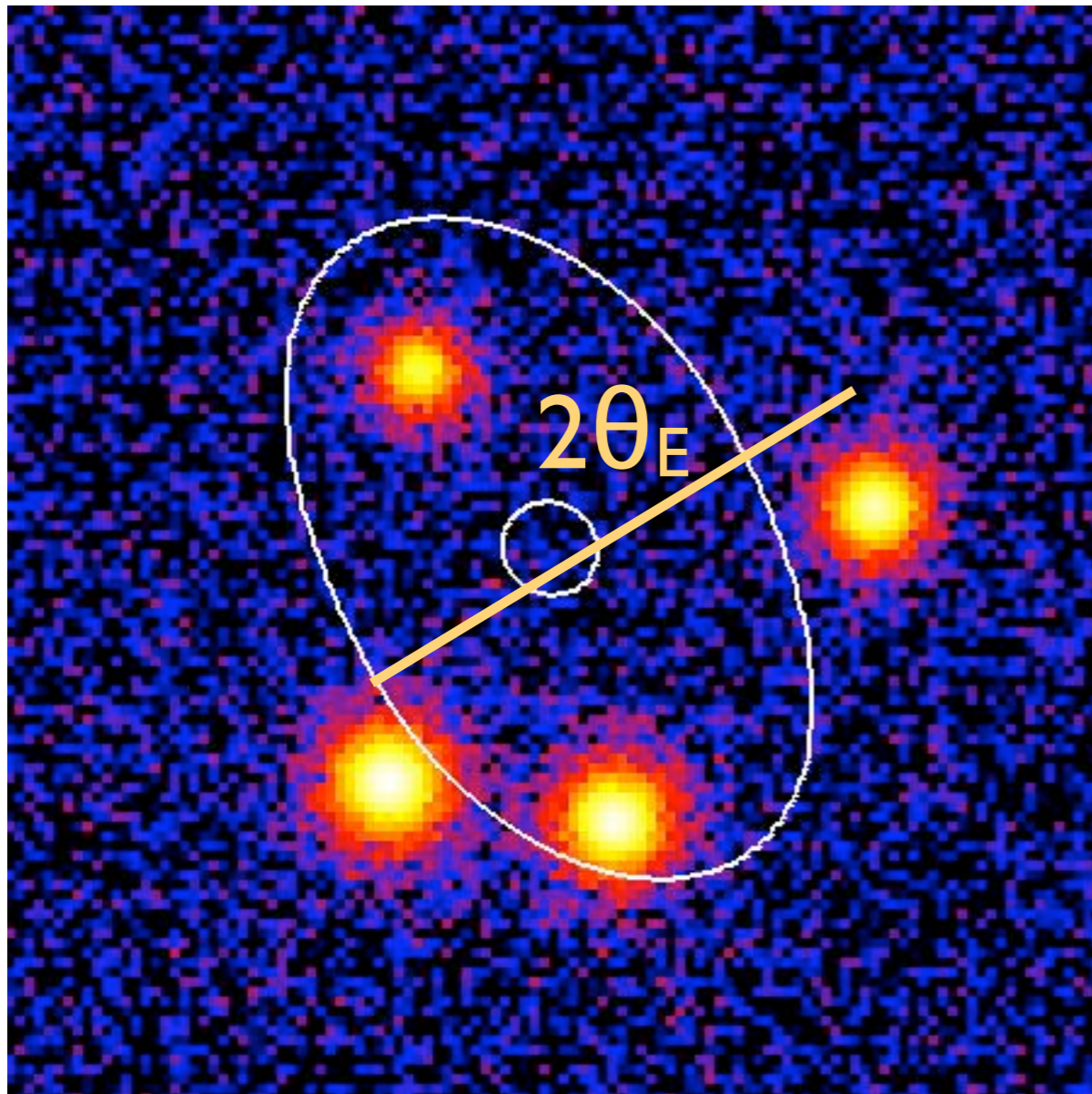
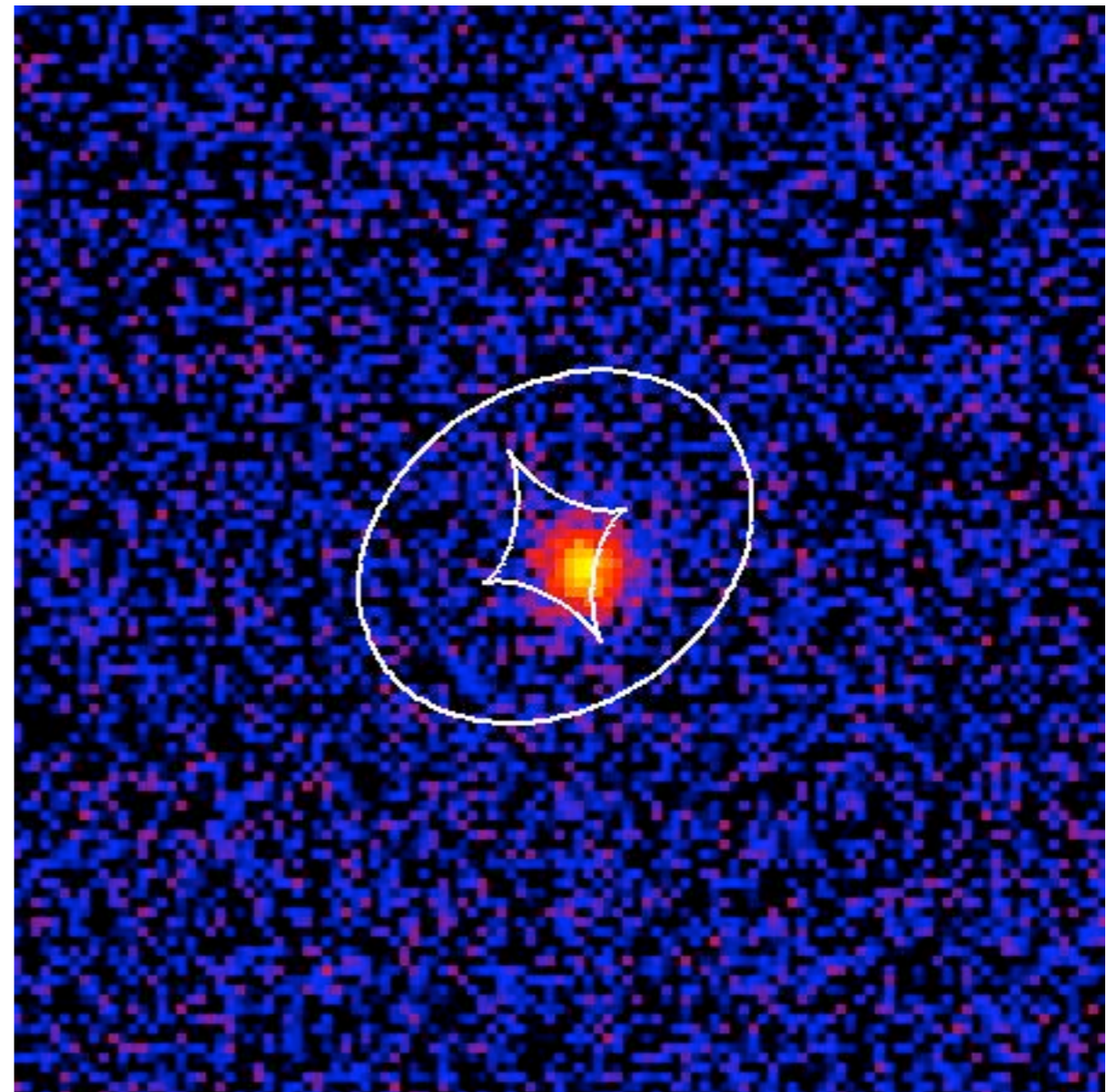


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

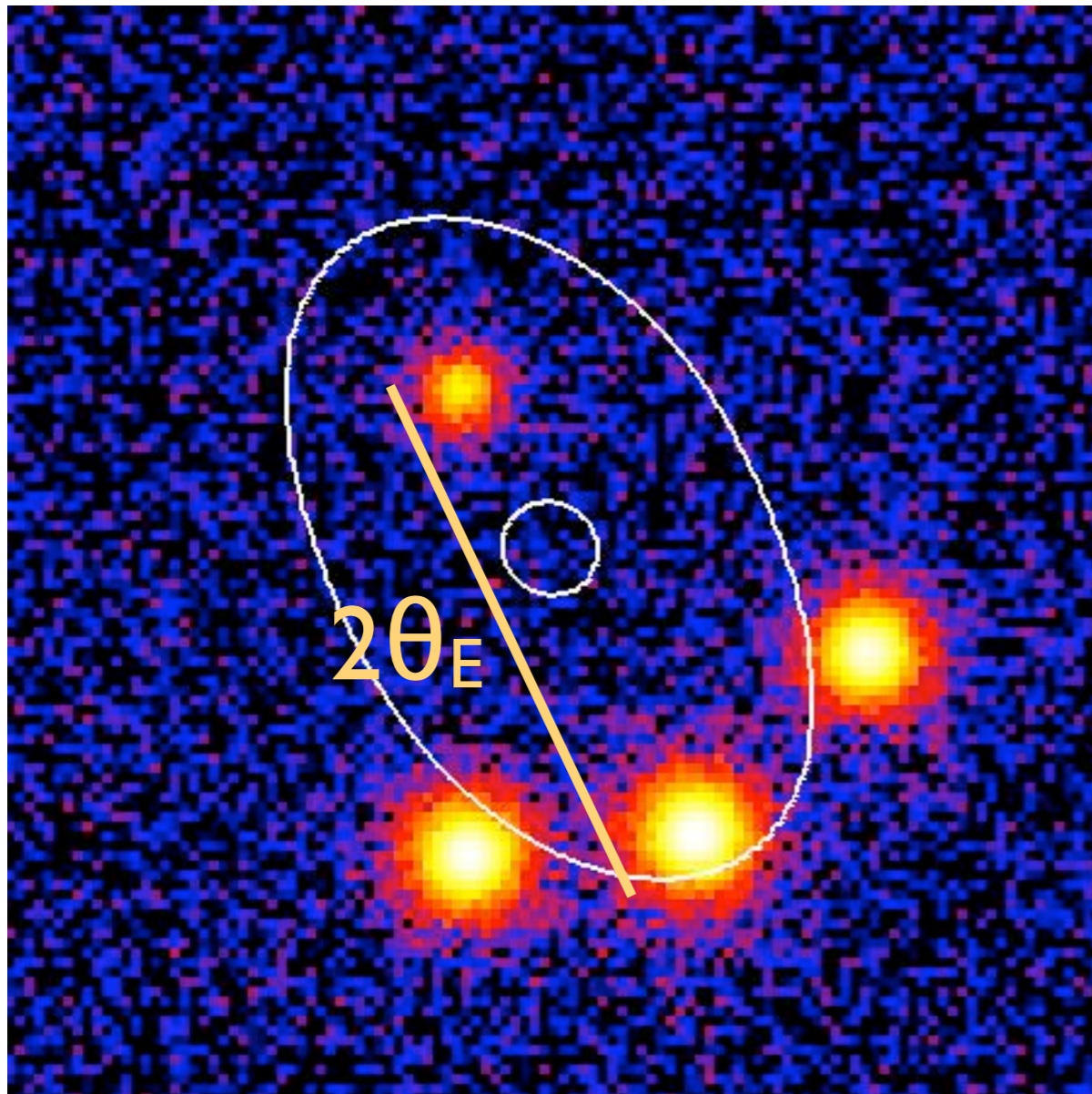
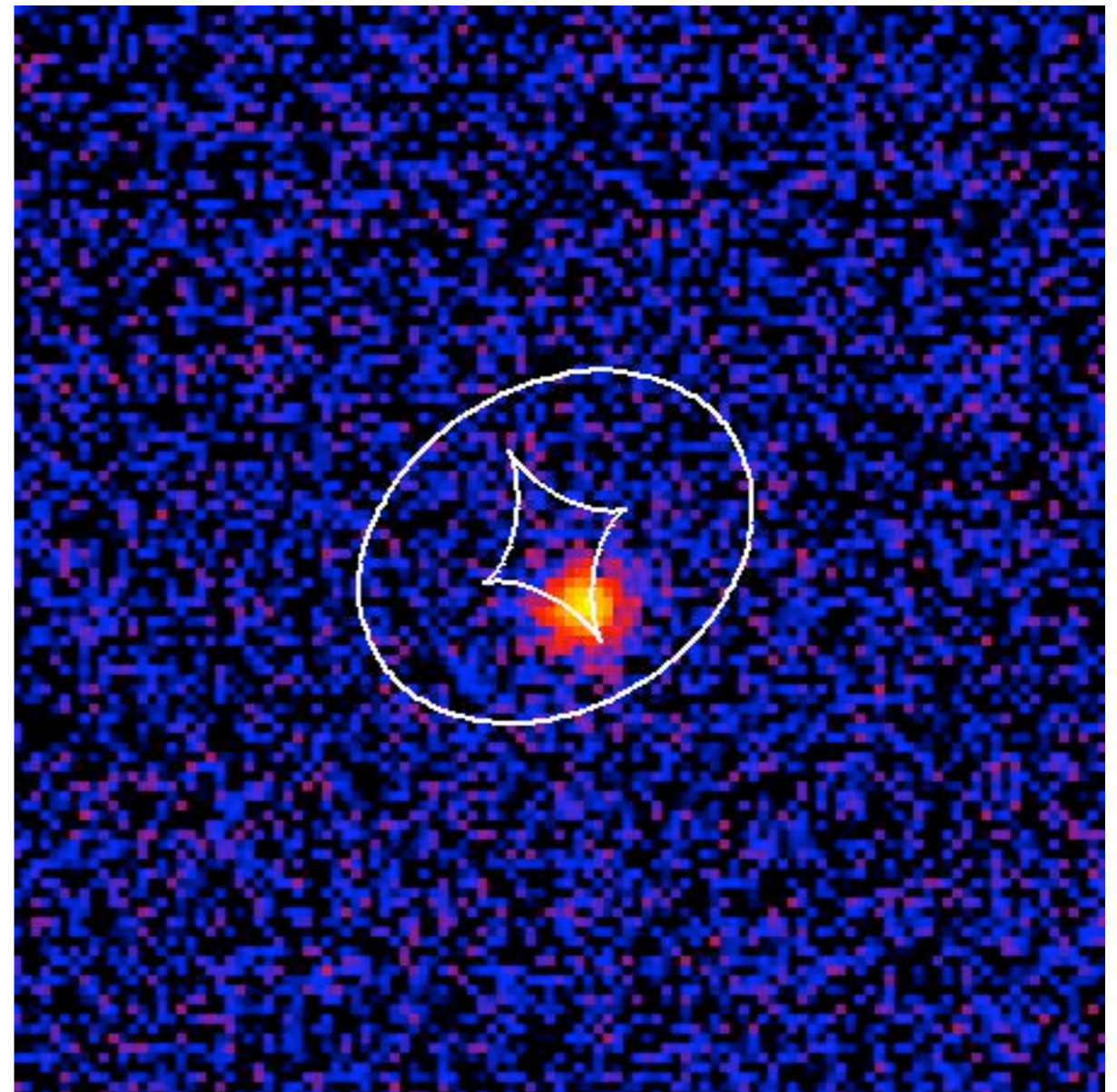


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

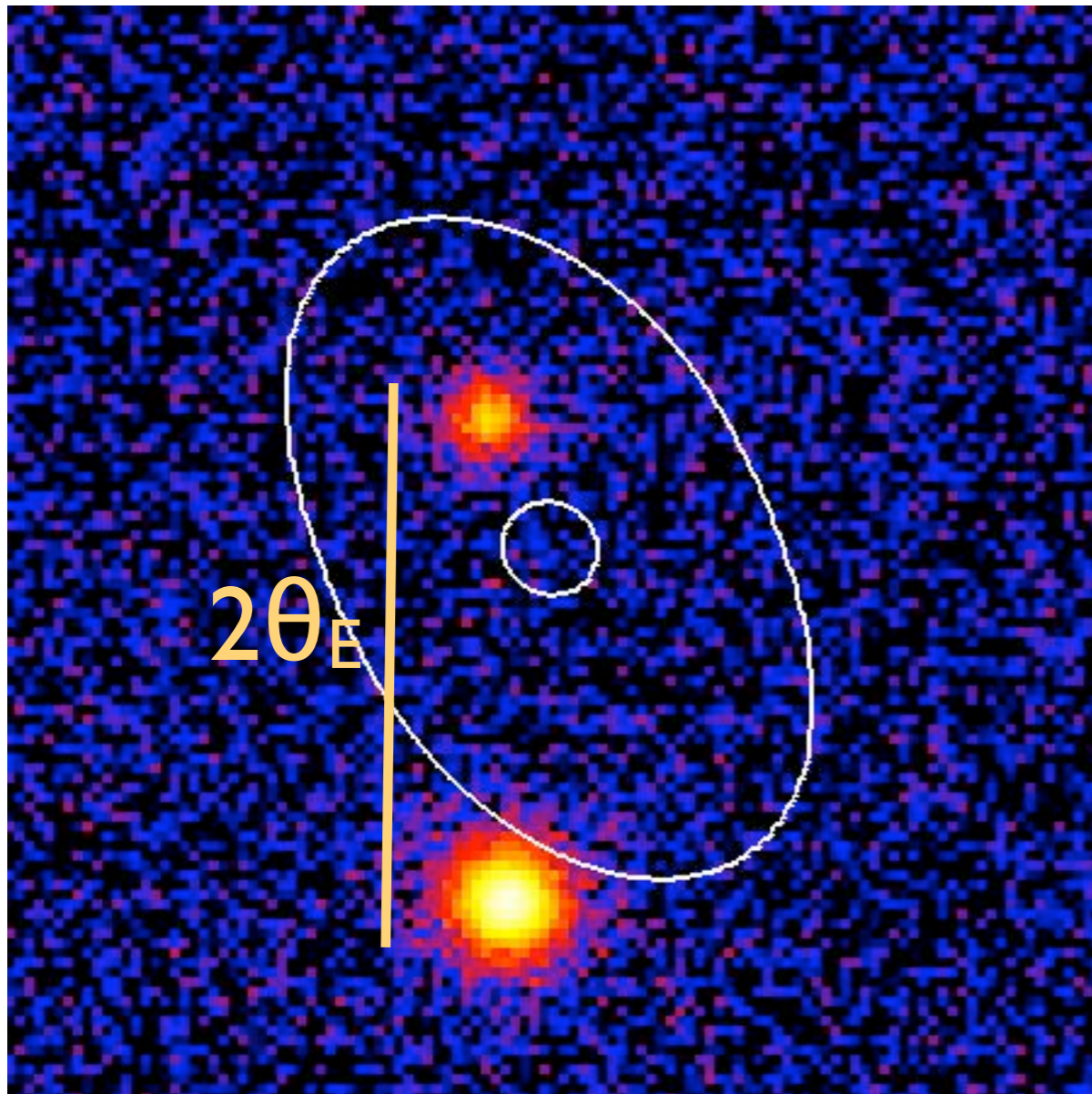
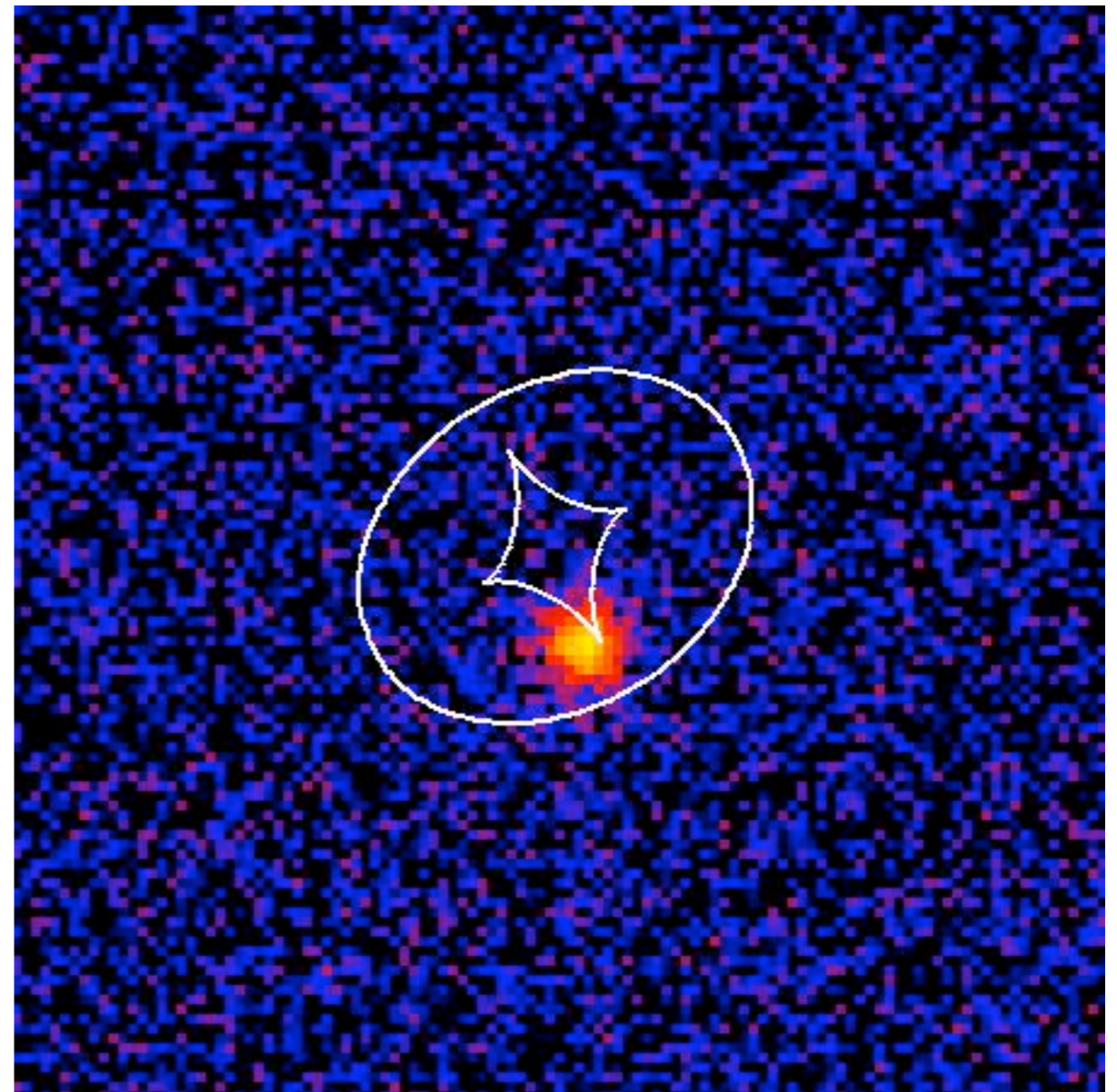


image plane
(critical curves)



source plane
(caustics)

Image separation and Einstein radius

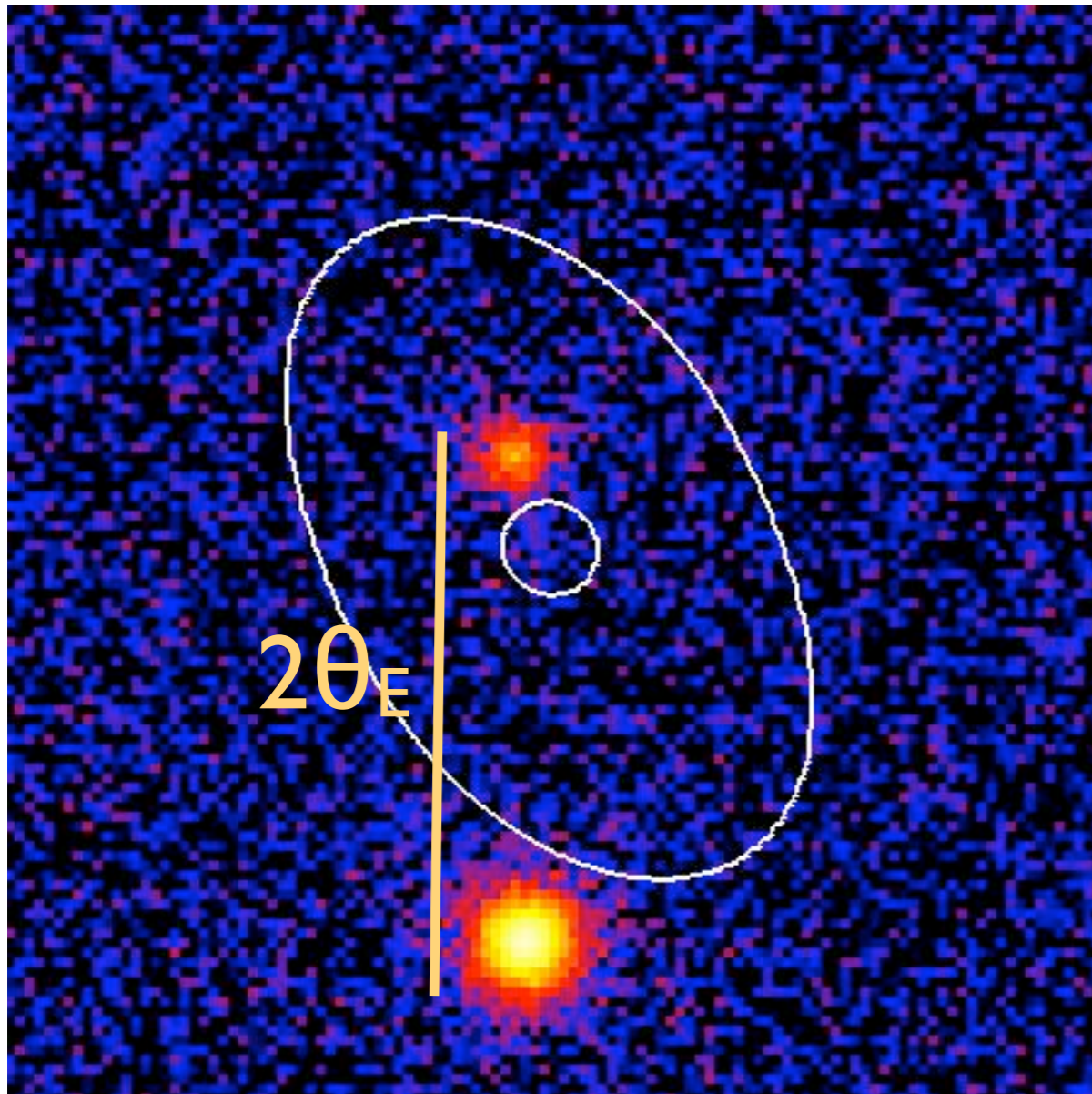
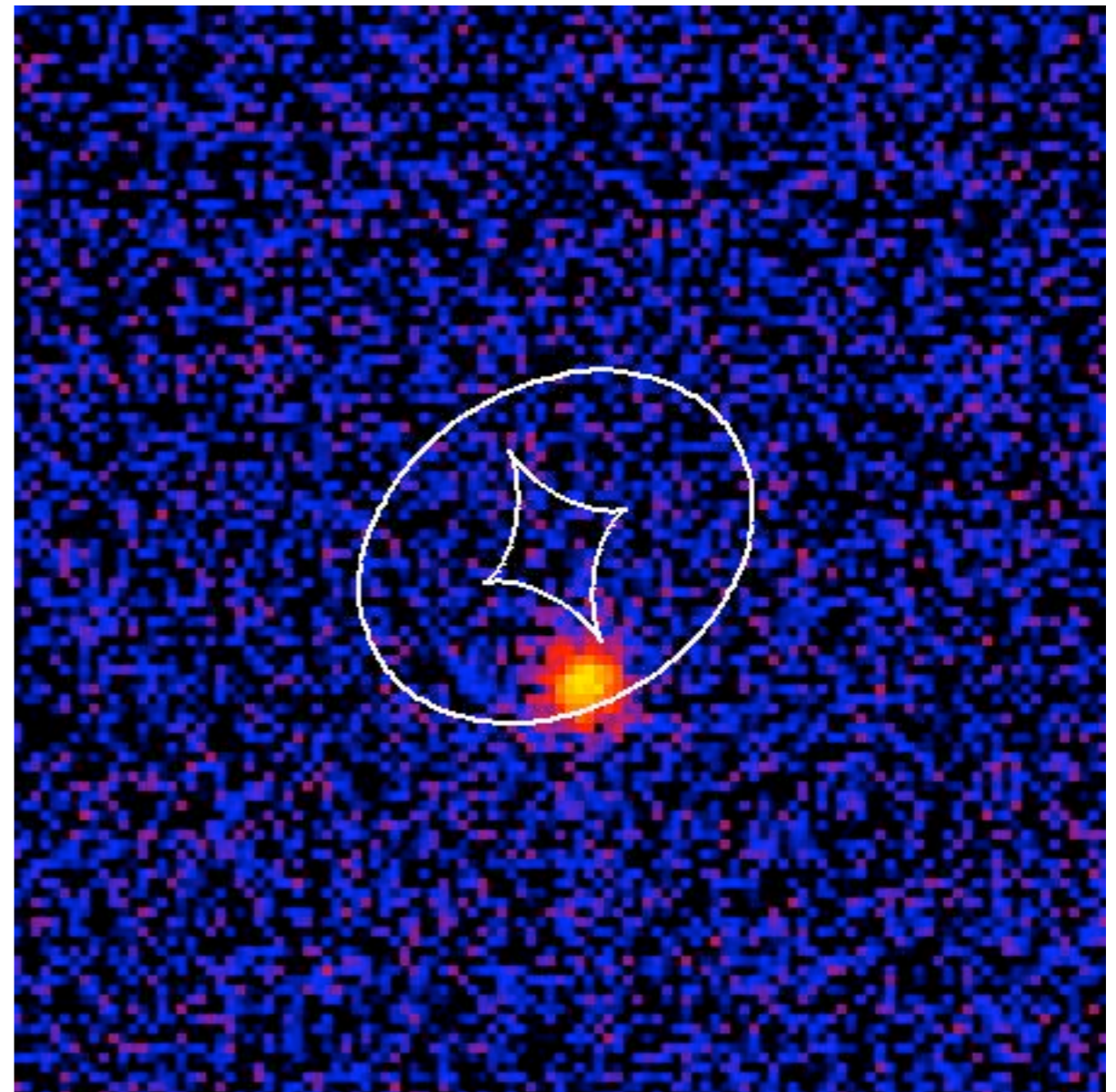


image plane
(critical curves)



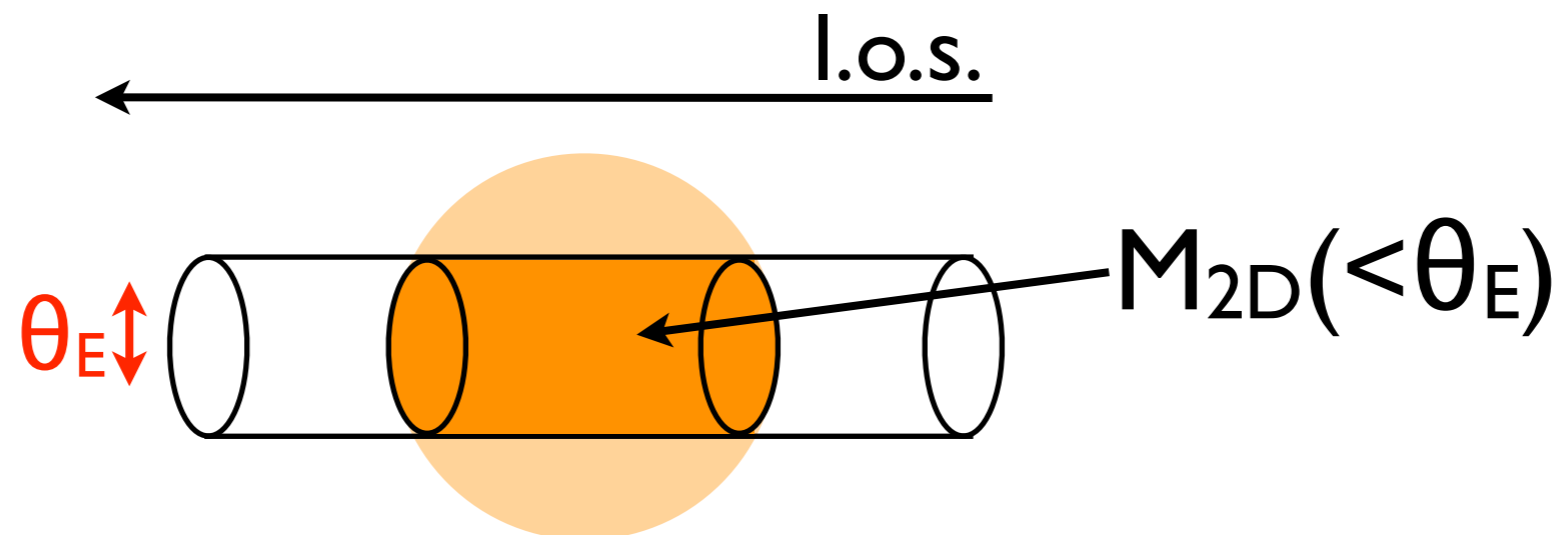
source plane
(caustics)

What does strong lens measure? (II)

- recall: the Einstein radius θ_E is determined by

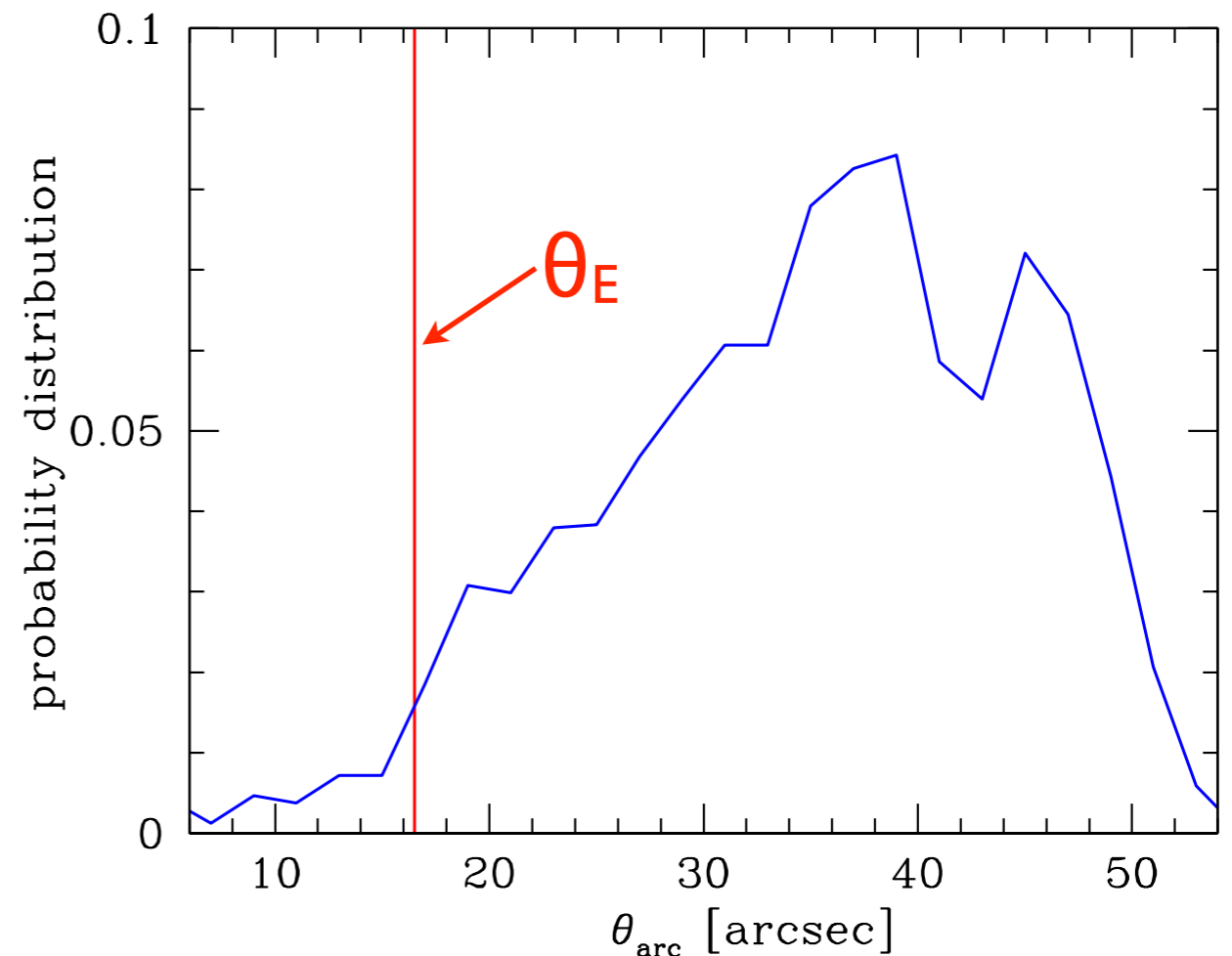
$$1 = \bar{\kappa}(< \theta_E) = \frac{M_{2D}(< \theta_E)}{\pi \theta_E^2 D_A^2(z_l) \Sigma_{\text{cr}}}$$

→ strong lensing well constrains projected 2D mass within Einstein radius, $M_{2D}(< \theta_E)$



Note: position of arcs

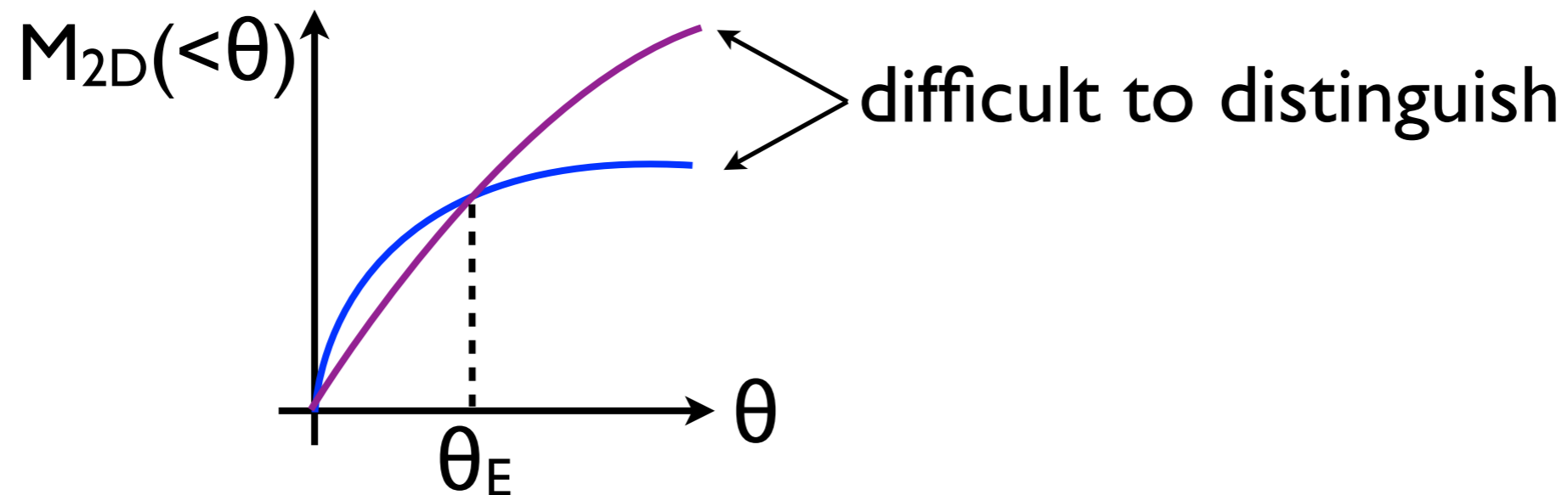
- sometimes people take positions of arcs θ_{arc} and assume $\theta_{\text{arc}} = \theta_E$
- this can be quite wrong, because arcs can be produced in asymmetric configurations, and arcs are produced preferentially along the major axis...



distribution of θ_{arc} for massive cluster with $e=0.4$ (simulated by *glafic*)

What does strong lens measure? (III)

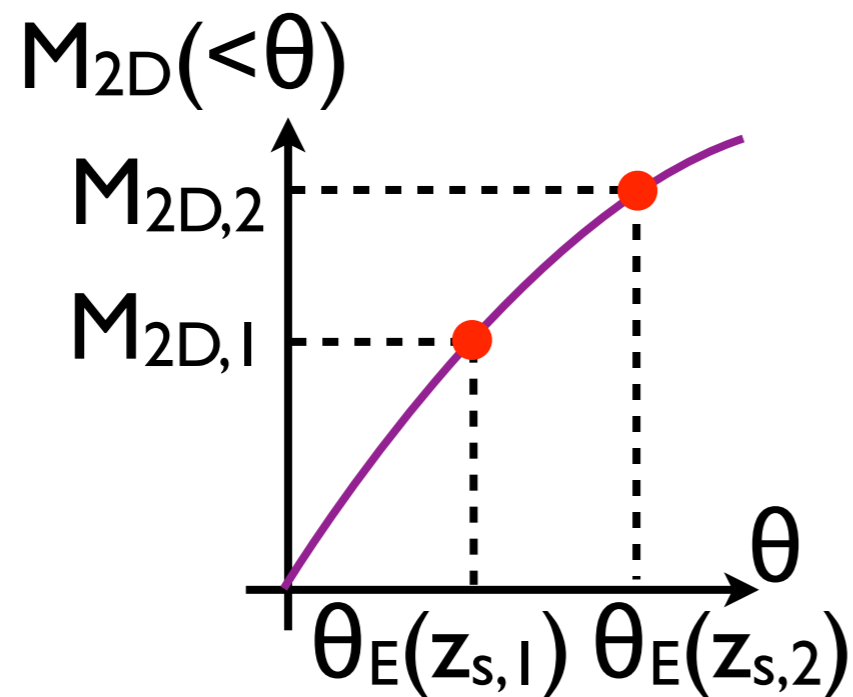
- on the other hand, radial density profile is usually not very well constrained



- possible ways to constrain radial profiles
 - (1) strong lenses with different z_s
 - (2) more constraints (time delays, arcs, ...)
 - (3) complementary mass probes (velocity dispersion, weak lensing, ...)

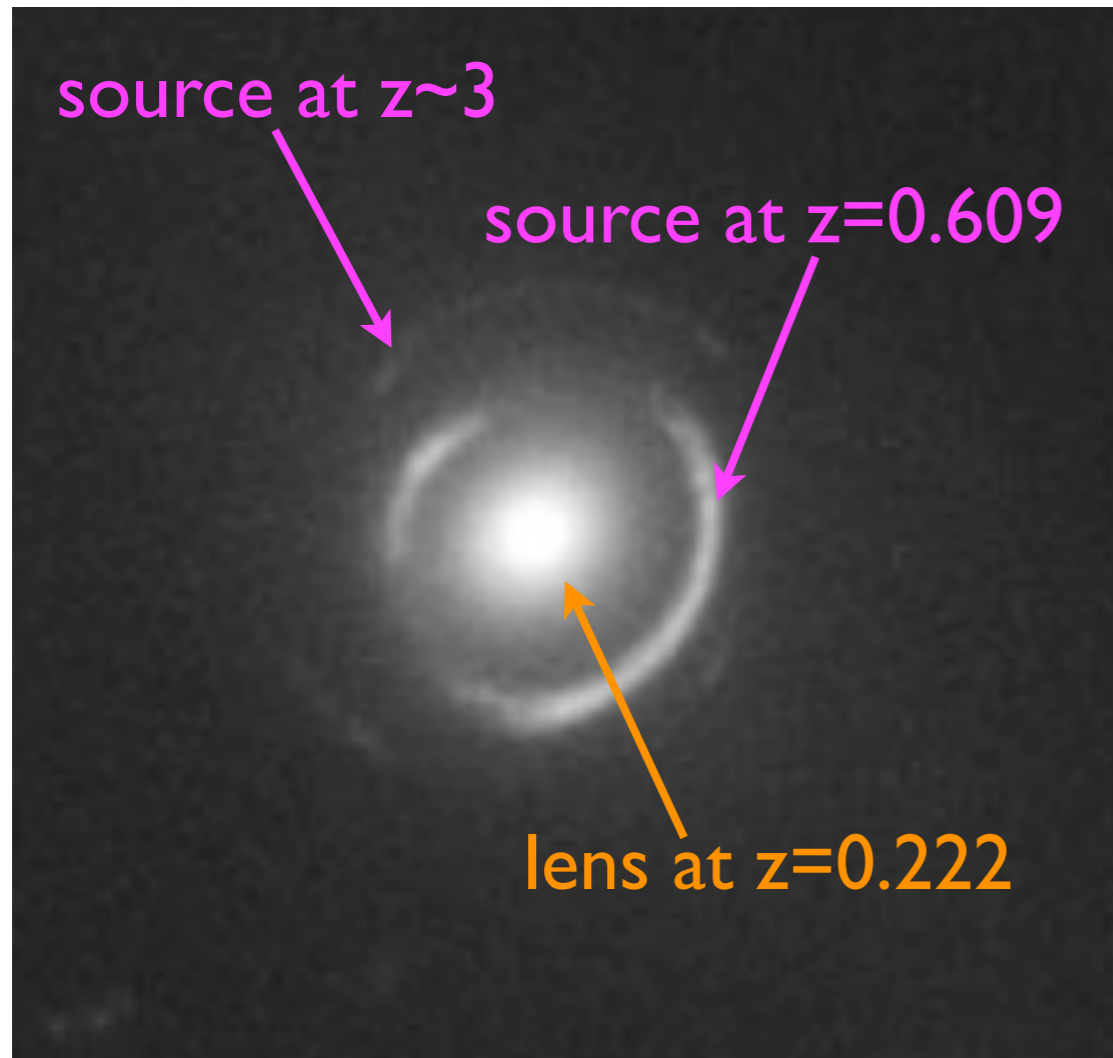
Multiple z_s

- multiple strongly lens systems in a same lens constrains enclosed masses at different radii

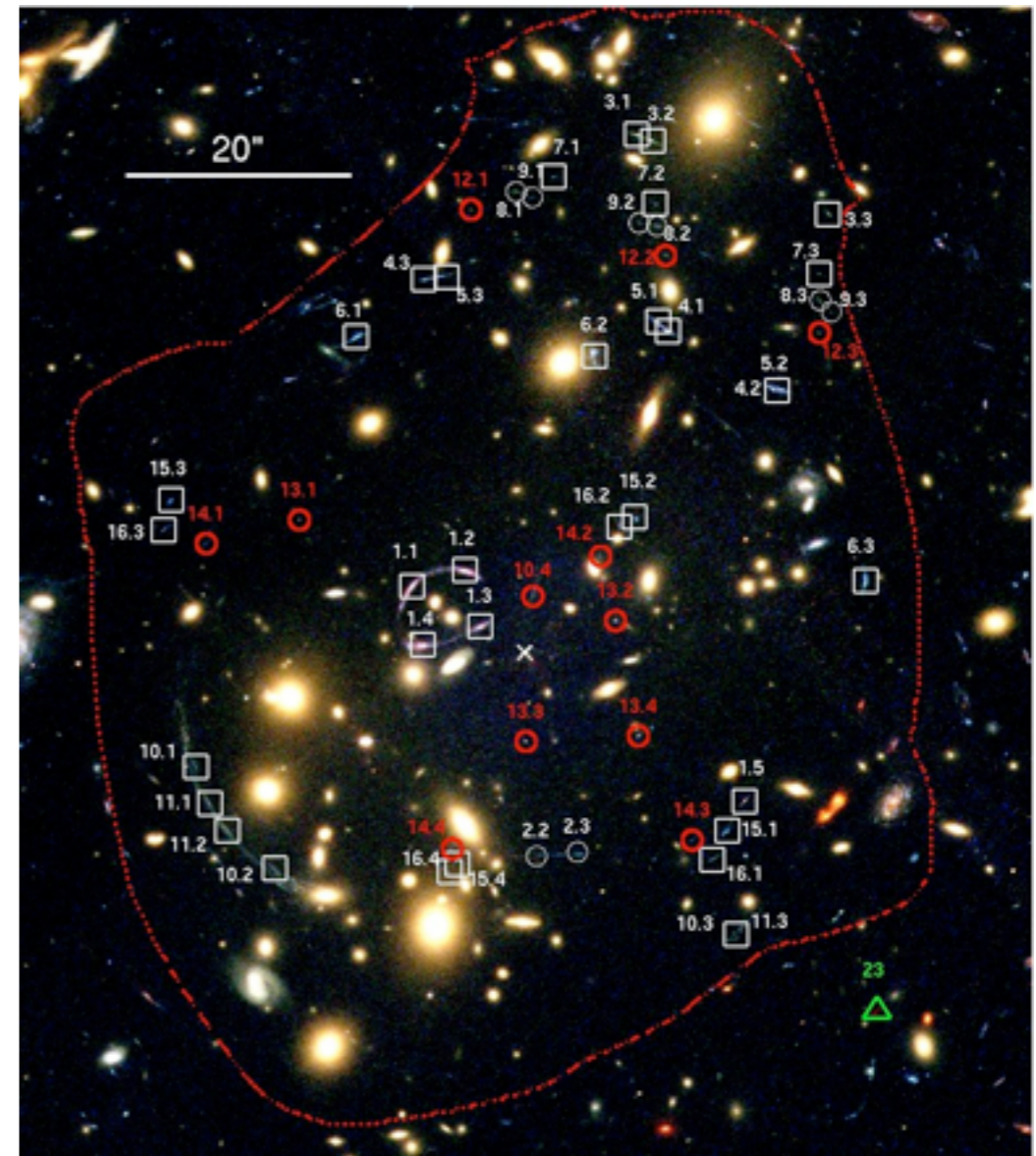


- useful to constrain radial profiles, and possibly cosmological parameters as well, particularly if combined with other radial profile probes

Multiple z_s : examples



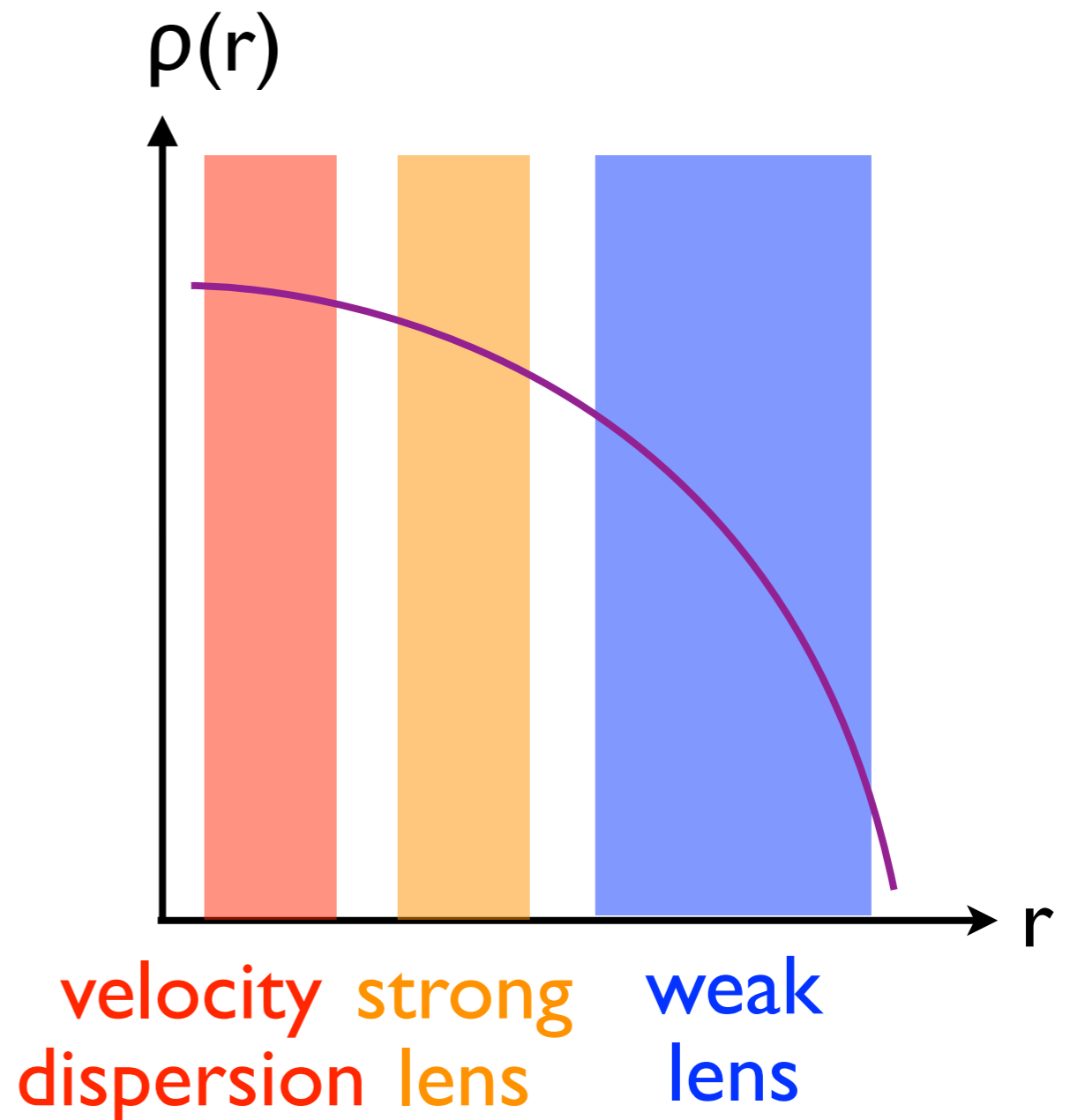
SDSSJ0946+1006
'double Einstein ring'
(Gavazzi et al. 2008)



Abell 1703
(Richard et al. 2009;
Oguri et al. 2009)

Multiple probes

- velocity dispersion
→ probe total mass at the very core
- weak lensing
→ probe outskirts of halos
(next lecture!)



Summary

- solving lens equation in general is not easy (need sophisticated numerical techniques)
- behavior is easier to understand for circular symmetric cases
- strong lens systems essentially probe enclosed mass within the Einstein radius

Contents

1. Introduction & basics of gravitational lensing
2. Strong lensing analysis
3. Weak lensing analysis
4. Cosmological applications